

review session 3/10 from

10:30 - 11:45

A graph  $G = (V, E)$

vertices

edges

(a set of  
abstract objects.

choose whatever

objects are useful

for your application!)

(undirected:  
unordered pairs  
of vertices

directed:  
ordered pairs)

undirected edges  $uv$

directed edge  $u \rightarrow v$

this notation mostly works  
just for simple graphs

(no loops or multi-edges)

$u \rightarrow u$  or  $uu$

We'll assume (usually) graphs are simple

most algorithms generalize cleanly to not-simple graphs

- if  $uv$  is an edge, we say  $v$  is a neighbor of  $u$

- if  $u \rightarrow v$  is a directed edge, 1)  $u$  is a predecessor of  $v$

2)  $v$  is a successor of  $u$

- in-degree of  $u$  is # of pred.s

- out-degree of  $u$  is # of successors

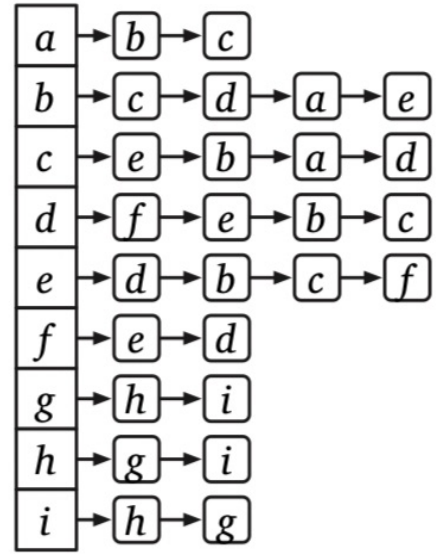
may use  $V$  or  $E$  to denote the number of vertices or edges

(depth-first search takes  $O(V+E)$  time)

Representations / Data structures

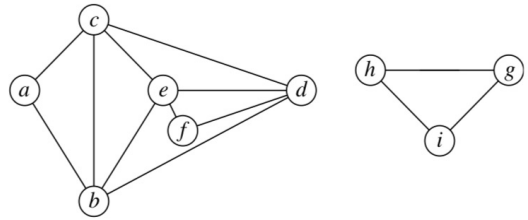
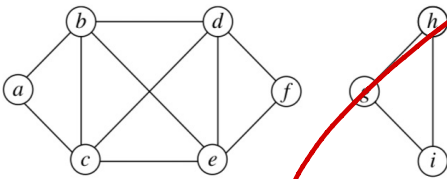
adjacency

	a	b	c	d	e	f	g	h	i
a	0	1	1	0	0	0	0	0	0
b	1	0	1	1	1	0	0	0	0
c	1	1	0	1	1	0	0	0	0
d	0	1	1	0	1	1	0	0	0
e	0	1	1	1	0	1	0	0	0
f	0	0	0	1	1	0	0	0	0
g	0	0	0	0	0	0	0	1	0
h	0	0	0	0	0	0	1	0	1
i	0	0	0	0	0	0	1	1	0



adjacency matrix  $\Theta(V^2)$  space

adjacency list



size  $\Theta(V+E)$   
 iterate over neighbors of  $u$   
 in  $O(1 + \text{deg}(u))$

degree graphs use lists of successors

# BFS

Given  $G = (V, E)$ ,

?; Is vertex  $v$  reachable  
from  $s$  (is there a path  
from  $s$  to  $v$ ),

## Breadth-first search (BFS)

visits vertices in increasing  
order of distance from  $s$

↑ # edges

mark visited vertices so  
we don't repeat work  
initially, all vertices  
unmarked

BFS( $s$ ): search from any  $s \in V$  (FIFO queue)

put  $(\emptyset, s)$  in a queue

while the queue is not empty

take  $(p, v)$  from the queue  
if  $v$  is unmarked

mark  $v$

parent  $(v) \leftarrow p$

for each edge  $vw$

put  $(v, w)$  in the queue

Can prove:

1) marks every vertex reachable from  $s$  exactly once

2) Set of pairs  $(v, \text{parent}(v))$  form a spanning tree on the component of  $G$  containing  $s$  (all those reachable vertices)

3) Paths from  $s$  within spanning tree are shortest paths to each marked vertex (unit edge weights)

analysis: we run the for loop  $\leq V$  times

$\Rightarrow$  Each edge added to queue twice. So  $\leq 2E+1$  enqueues

$\Rightarrow \leq 2E+1$  dequeues

So... total time at...

$O(E)$  time

- if graph is directed, loop over successors at  $v$ .

- how spanning tree over vertices reachable from  $s$  (with  $s$  as root)

· USE BFS TO FIND UNWEIGHTED

SHORTEST PATHS!

(not Dijkstra)



# Depth-first search (DFS):

DFS( $v$ ):

mark  $v$

*PREVISIT*( $v$ )

for each edge  $vw$

if  $w$  is unmarked

$\text{parent}(w) \leftarrow v$

    DFS( $w$ )

*POSTVISIT*( $v$ )

DFSALL( $G$ ):

*PREPROCESS*( $G$ )

for all vertices  $v$

    unmark  $v$

for all vertices  $v$

    if  $v$  is unmarked

        DFS( $v$ )

DFSALL marks each vertex once. Sees each edge twice (or once if  $G$  is directed).  
Runs in  $O(V + E)$ .