

CS 7301.003.20F Lecture 26–November 16, 2020

Main topics are `#persistent_homology`, `#stability`, and `#curves`.

- Today, we're going to recast stability of persistence in terms of continuous functions. Then we'll see a surprising application of stability to the length and curvature of two curves.

Sublevel Sets

- Let X be a topological space and $g : X \rightarrow \mathbb{R}$ be a continuous function.
- Given a threshold a in \mathbb{R} , the *sublevel set* at a is the points in X with function value at most a , denoted as $X_a = g^{-1}(-\infty, a]$.
- Similar to complexes in a filtration, the sublevel sets are nested and give rise to sequences of homology groups, one per dimension.
- Let $f^{[a, b]}_k : H_k(X_a) \rightarrow H_k(X_b)$ be the map induced by inclusion for homology groups of a and b 's sublevel sets. Its image is a *persistent homology group* and the *persistent Betti number* $\beta^{[a, b]}_k = \text{rank im } f^{[a, b]}_k$.
- Now, let's find a definition for persistence diagrams.
- We call a in \mathbb{R} a *homological critical value* if there is no $\epsilon > 0$ for which $f^{[a - \epsilon, a + \epsilon]}_k$ is an isomorphism for each dimension p , i.e., homology changes precisely at threshold a .
- Function g is *tame* if there are finitely many homological critical values and every sublevel set has finite rank homology groups.
- Let $a_1 < a_2 < \dots < a_n$ be the homological critical values and $b_0 < b_1 < \dots < b_n$ be interleaved values such that $b_{i-1} < a_i < b_i$ for $1 \leq i \leq n$.
- All of the k -dimensional homology groups can now be expressed as

$$0 = H^{[b_{-1}]}_k \rightarrow H^{[b_0]}_k \rightarrow H^{[b_1]}_k \rightarrow \dots \rightarrow H^{[b_n]}_k \rightarrow H^{[b_{n+1}]}_k = 0.$$

- For convenience, let $a_0 = -\infty$ and $a_{n+1} = \infty$.
- For $0 \leq i < j \leq n + 1$, the *multiplicity* of the pair (a_i, a_j) can be defined as

$$\mu_p^{i,j} = (\beta_p^{b_i, b_{j-1}} - \beta_p^{b_i, b_j}) - (\beta_p^{b_{i-1}, b_{j-1}} - \beta_p^{b_{i-1}, b_j}).$$

(except use k instead of p).

- In the *dimension k persistence diagram* of g , we draw each point (a_i, a_j) with multiplicity $\mu^{[i, j]}_k$.
- Unlike with filtrations, we can have multiplicities other than 0 and 1. We may also have points at infinity. For example, if g is bounded, we may birth 0-dimensional homology classes that never die, meaning they correspond to points with a second coordinate of ∞ .
- We can define bottleneck distance exactly as yesterday and get the same stability

theorem. I won't prove this theorem.

- Stability Theorem for Functions: Let X be a triangulable topological space, $g, g_0 : X \rightarrow \mathbb{R}$ two tame functions, and k any dimension. Then $d_B(Dgm_k(g), Dgm_k(g_0)) \leq \|g - g_0\|_{\infty}$.

Curvature of Cycles

- We're now going to shift gears a bit by discussing curvature of cycles.
- Let $\gamma : S^1 \rightarrow \mathbb{R}^2$ be a smooth cycle with derivative of all orders. It may have self intersections.
- The *speed at a point* $\gamma(s)$ is the magnitude of the velocity vector, $\|\gamma'(s)\|$. The length of γ is therefore $L(\gamma) = \int_{s \in S^1} \|\gamma'(s)\| ds$.
- Let's assume γ has a constant speed parameterization, so $v = \|\gamma'(s)\| = 1 / (2\pi) L(\gamma)$ for all $s \in S^1$.
- The *curvature at a point* $\gamma(s)$ is defined as $\kappa(s) = \|\gamma''(s)\| / v^2$.
- Imagine the velocity vector as we trace along the curve. It's length is constant, so it sweeps along a circle of radius v .
- The curvature is the speed at which the unit tangent vector sweeps out the unit circle as we move the point with unit speed along the curve. That's why we divide by the speed twice: first to compensate for the length of the velocity vector and second to to compensate for the actual speed we move along γ .
- The *total curvature* of γ is the distance swept by the unit tangent vector

$$K(\gamma) = \int_{s \in S^1} v \kappa(s) ds$$
- As a simple example, the circle of radius r has total length $2\pi r$ and total curvature 2π . Edelsbrunner does the actual calculations in his notes.
- There's another way we can derive length and curvature using intersections with lines in the plane and maxima and minima in various directions.
- Consider a unit length segment in the plane. The set of lines crossing the segment at angle ϕ form a strip of width $\sin \phi$. If we integrate over all angles, we get $\int_0^\pi \sin \phi d\phi = [-\cos \phi]_0^\pi = 2$. In other words, the total number of intersections with lines is twice the length of the segment.
- Let's extend the idea to a cycle by writing lines as the preimage of a linear function.
- Given a direction $u \in S^1$, let $h_u : \mathbb{R}^2 \rightarrow \mathbb{R}$ be defined as $h_u(x) = \langle u, x \rangle$. The line with normal direction u and offset z is $h_u^{-1}(z)$.
- The intersections between γ and this line correspond to the preimage of $h_u^{-1}(z)$ where composition $h = h_u \circ \gamma$.
- Therefore, the length of the curve is the Cauchy-Crofton formula:

$$L(\gamma) = \frac{1}{4} \int_{u \in S^1} \int_{z \in \mathbb{R}} \text{card}(h^{-1}(z)) dz du.$$

We divide by 2 to account for the doubling of the length discussed earlier and divide by 2 again, because each slope is represented by u and $-u$.

- Now for curvature, again let u in S^1 , but overload $h_u : S^1 \rightarrow \mathbb{R}$ as the height function in that direction $h_u(s) = \langle u, \gamma(s) \rangle$.
- For generic u , this height function has a finite number of local maxima and minima.
- We can define curvature as the length of circle traveled by the outward unit normal vector (as opposed to tangent vector). The number of maxima of h_u is the number of times the unit normal passes over u in S^1 , and the minima is the number of times it passes over $-u$ in S^1 .
- Let $c(h_u)$ be the number of maxima and minima of h_u . We have

$$K(\gamma) = \frac{1}{2} \int_{u \in S^1} c(h_u) du.$$

Relating Length to Total Curvature

- Suppose γ fits entirely within the unit disk in the plane, i.e. $\text{im } \gamma \subseteq B^2$. Then γ must turn a lot to fit within the disk. Fáry's Theorem states $L(\gamma) \leq K(\gamma)$ in this case.
- There's a generalization of this theorem involving two smooth cycles $\gamma, \gamma_0 : S^1 \rightarrow \mathbb{R}^2$ (not necessarily in B^2).
- We define (for this lecture) the *Fréchet distance* between them as the infimum over all homeomorphisms the largest distance between corresponding points.
 - $d_F(\gamma, \gamma_0) = \inf_{\eta} \max_u \|\gamma(u) - \gamma_0(\eta(u))\|$ where $\eta : S^1 \rightarrow S^1$ is a homeomorphism and u in S^1 .
- Generalized Fáry Theorem: Let $\gamma, \gamma_0 : S^1 \rightarrow \mathbb{R}^2$ be two smooth cycles. Then $|L(\gamma) - L(\gamma_0)| \leq [K(\gamma) + K(\gamma_0) - 2\pi] d_F(\gamma, \gamma_0)$.
- For example, if we take γ_0 to be an arbitrarily tiny circle centered at the origin and $\text{im } \gamma \subseteq B^2$, then $L(\gamma_0)$ approaches 0, $K(\gamma_0) = 2\pi$, and $d_F(\gamma, \gamma_0)$ approaches at most 1. We get the original Fáry Theorem.
- Surprisingly, we'll prove this theorem by using everything we know about persistent homology.
- Fix a direction u in S^1 and let $h = h_u \circ \gamma$ and $h_0 = h_u \circ \gamma_0$ be the restrictions to the height functions to the curves.
- Almost all level sets of the form $h^{-1}(z)$ consist of an even number of points decomposing γ into the same number of arcs. Half of these live in $h^{-1}(-\infty, z]$.
- Let $\chi(z)$ be the Euler characteristic of the sublevel set for z . It's equal to number of points in $h^{-1}(z)$ minus the number of arcs in $h^{-1}(-\infty, z]$, which again is half that number of points. Therefore,

$$\int_{z \in \mathbb{R}} \text{card}(h^{-1}(z)) dz = 2 \int_{z \in \mathbb{R}} \chi(z) dz$$

- So if we want to study the difference of lengths, we can study the difference of integrals over $\text{card}(h^{-1})$ or the difference in these Euler characteristics.
- By the Euler-Poincaré formula, the Euler characteristic of a sublevel set is the number of components (β_0) minus number of loops (β_1).
- Therefore, $\chi(z)$ is the number of points in $\text{Dgm}_0(h)$ within quadrant $Q_z = (-\infty, z] \times (z, \infty)$ minus the number of points in $\text{Dgm}_1(h)$ within the same quadrant.
- Let χ_0 be the Euler characteristic for γ_0 . We can say the same things here.
- Now let's compare those persistence diagrams. Let $\epsilon = d_F(\gamma, \gamma_0)$ and $\eta : S^1 \rightarrow S^1$ a homeomorphism such that the Euclidean distance between points $\gamma(s)$ and $\gamma_0(\eta(s))$ is at most $\epsilon + \delta$.
- The stability of persistence diagrams implies the bottleneck distance between $\text{Dgm}_0(h)$ and $\text{Dgm}_0(h_0)$ is at most $\epsilon + \delta$, and the same holds for the Dgm_1 . Let ψ_0 and ψ_1 be the corresponding bijections between the bottleneck diagrams.
- Now observe that the contributions of points v in $\text{Dgm}_k(h)$ and $\psi_k(v)$ in $\text{Dgm}_k(h_0)$ cancel each other out except for values of z for which one point lies inside the quadrant Q_z and the other lies outside. For pairs of finite points, the integral over such values of z is at most $2(\epsilon + \delta)$.
- Note finite points in one diagram may be matched to the fake points in the diagonal of the other diagram. Each coordinate of a finite point contributes at most $\epsilon + \delta$ to the integral.
- However, points at infinity must be matched to each other and we have exactly four; one each in the two diagrams of h and the two diagrams of h_0 . The integral over values of z for which one point of a pair is in the quadrant here is at most $\epsilon + \delta$. So the total contribution from these finite coordinates is $2(\epsilon + \delta)$, which is $(\epsilon + \delta)$ times the number of their finite coordinates minus 2.
- In other words, we get a contribution of at most $\epsilon + \delta$ for each minimum and maximum of h and h_0 , except for two.
- Taking δ to 0 and using the Cauchy-Crofton formula, we get

$$\begin{aligned} |L(h) - L(h_0)| &\leq \frac{1}{4} \int_{u \in S^1} \int_{z \in \mathbb{R}} |\text{card } h^{-1}(z) - \text{card } h_0^{-1}(z)| dz du \\ &\leq \frac{1}{2} \int_{u \in S^1} \int_{z \in \mathbb{R}} |\chi(z) - \chi_0(z)| dz du \\ &\leq \frac{\epsilon}{2} \int_{u \in S^1} [c(h) + c(h_0) - 2] du. \end{aligned}$$

- Finally, plug in the formula we saw for total curvature to reduce the right hand side to $\epsilon[K(\gamma) + K(\gamma_0) - 2\pi]$.