

More Learning Theory

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Based on the slides of Vibhav Gogate and David Sontag

Last Time



- Probably approximately correct (PAC)
 - The only reasonable expectation of a learner is that with high probability it learns a close approximation to the target concept
 - Specify two small parameters, $0 < \epsilon$, $0 < \delta < 1$
 - ϵ is the error of the approximation
 - $(1-\delta)$ is the probability that, given M i.i.d. samples, our learning algorithm produces a classifier with error at most ϵ

Learning Theory



- We use the observed data in order to learn a classifier
- Want to know how far the learned classifier deviates from the (unknown) underlying distribution
 - With too few samples, we will with high probability learn a classifier whose true error is quite high even though it may be a perfect classifier for the observed data
 - As we see more samples, we pick a classifier from the hypothesis space with low training error & hope that it also has low true error
 - Want this to be true with high probability can we bound how many samples that we need?

Haussler, 1988



What we proved last time:

Theorem: For a finite hypothesis space, H, with M i.i.d. samples, and $0 < \epsilon < 1$, the probability that any consistent classifier has true error larger than ϵ is at most $|H|e^{-\epsilon M}$

We can turn this into a sample complexity bound

Sample Complexity



- Let δ be an upper bound on the desired probability of not ϵ -exhausting the sample space
 - The probability that the version space is not ϵ -exhausted is at most $|H|e^{-\epsilon M} \leq \delta$
 - Solving for M yields

$$M \ge -\frac{1}{\epsilon} \ln \frac{\delta}{|H|}$$
$$= \left(\ln |H| + \ln \frac{1}{\delta} \right) / \epsilon$$



- Our analysis for the finite case was based on |H|
 - If *H* isn't finite, this translates into infinite sample complexity
 - We can derive a different notion of complexity for infinite hypothesis spaces by considering only the number of points that can be correctly classified by some member of H
 - We will only consider the binary classification case for now



- How many points in 1-D can be correctly classified by a linear separator?
 - 2 points:





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- How many points in 1-D can be correctly classified by a linear separator?
 - 3 points:





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 - 3 points:



• 3 points and up: for any collection of three or more there is always some choice of pluses and minuses such that the points cannot be classified with a linear separator (in one dimension)



- A set of points is shattered by a hypothesis space H if and only if for every partition of the set of points into positive and negative examples, there exists some consistent h ∈ H
- The Vapnik-Chervonenkis (VC) dimension of H over inputs from X is the size of the largest finite subset of X shattered by H



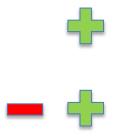
- Common misconception:
 - VC dimension is determined by the largest shattered set of points, not the highest number such that all sets of points that size can be shattered



Cannot be shattered by a line



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 - VC dimension is determined by the largest shattered set of points, not the highest number such that all sets of points that size can be shattered



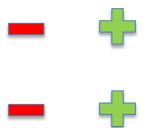
Can be shattered by a line (no matter the labels), so VC dimension is at least 3



- What is the VC dimension of 2-D space under linear separators?
 - It is at least three from the last slide
 - Can some set of four points be shattered?

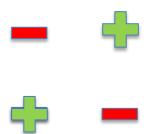


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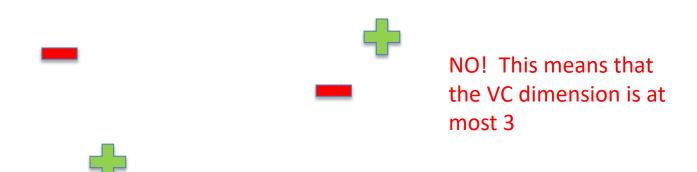


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- There exists a set of size d+1 in a d-dimensional space that can be shattered by a linear separator, but not a set of size d+2
- The larger the subset of X that can be shattered, the more expressive the hypothesis space is
- If arbitrarily large finite subsets of X can be shattered, then $VC(H) = \infty$

Axis Parallel Rectangles



- Let X be the set of all points in \mathbb{R}^2
- Let H be the set of all axis parallel rectangles in 2-D (inside + outside -)
 - What is VC(H)?

Axis Parallel Rectangles



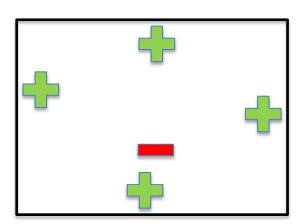
- Let X be the set of all points in \mathbb{R}^2
- Let H be the set of all axis parallel rectangles in 2-D (inside + outside -)
 - $VC(H) \ge 4$



Axis Parallel Rectangles



- Let X be the set of all points in \mathbb{R}^2
- Let H be the set of all axis parallel rectangles in 2-D
 - VC(H) = 4
 - A rectangle can contain at most 4 extreme points, the fifth point must be contained within the rectangle defined by these points





 VC dimension of one-level decision trees over real vectors of length 2?

VC dimension of linear separators through the origin?

• VC dimension of a hypothesis space with exactly one hypothesis in it for binary vectors of length $n \ge 1$?



- VC dimension of one-level decision trees over real vectors of length 2?
 - Three
- VC dimension of linear separators through the origin?

• VC dimension of a hypothesis space with exactly one hypothesis in it for binary vectors of length $n \ge 1$?



- VC dimension of one-level decision trees over real vectors of length 2?
 - Three
- VC dimension of linear separators through the origin?
 - Two
- VC dimension of a hypothesis space with exactly one hypothesis in it for binary vectors of length $n \ge 1$?



- VC dimension of one-level decision trees over real vectors of length 2?
 - Three
- VC dimension of linear separators through the origin?
 - Two
- VC dimension of a hypothesis space with exactly one hypothesis in it for binary vectors of length $n \ge 1$?
 - Zero

PAC Learning



• Given:

- Set of data X
- Hypothesis space H
- Set of target concepts C
- Training instances from unknown probability distribution over X of the form (x, c(x))

Goal:

• Learn the target concept $c \in C$

PAC Learning



- Given:
 - A concept class C over n instances from the set X
 - A learner L with hypothesis space H
 - Two constants, $\epsilon, \delta \in (0, \frac{1}{2})$
- C is said to be PAC learnable by L using H iff for all distributions over X, learner L by sampling n instances will with probability at least $1-\delta$ output a hypothesis $h\in H$ such that
 - $\epsilon_h \leq \epsilon$
 - Running time is polynomial in $\frac{1}{\epsilon}$, $\frac{1}{\delta}$, n, size(c)

PAC Bounds



Theorem: For a finite hypothesis space H, M i.i.d. samples, and $0 < \epsilon < 1$, the probability that true error of any of the best classifiers (i.e., lowest training error) is larger than its training error plus ϵ is at most $|H|e^{-2M\epsilon^2}$

• Sample complexity (for desired $\delta \ge |H|e^{-2M\epsilon^2}$)

$$M \ge \left(\ln|H| + \ln\frac{1}{\delta}\right)/2\epsilon^2$$

PAC Bounds



• If we require that the previous error is bounded above by δ , then with probability $(1 - \delta)$, for all $h \in H$

$$\epsilon_h \leq \epsilon_h^{train} + \sqrt{\frac{1}{2M} \left(\ln |H| + \ln \frac{1}{\delta} \right)}$$
 "bias" "variance"

- For small |H|
 - High bias (may not be enough hypotheses to choose from)
 - Low variance

PAC Bounds



• If we require that the previous error is bounded above by δ , then with probability $(1 - \delta)$, for all $h \in H$

$$\epsilon_h \leq \epsilon_h^{train} + \sqrt{\frac{1}{2M} \left(\ln |H| + \ln \frac{1}{\delta} \right)}$$
"bias"
"variance"

- For large |H|
 - Low bias (lots of good hypotheses)
 - High variance

PAC Bounds with VC Dimension



VC dimension can be used to construct PAC bounds

$$M \ge \frac{1}{\epsilon} \left(4 \ln \frac{2}{\delta} + 8 \cdot VC(H) \ln \frac{13}{\epsilon} \right)$$

• Then, with probability at least $(1 - \delta)$ every $h \in H$ satisfies

$$\epsilon_h \le \epsilon_h^{train} + \sqrt{\frac{1}{M} \left(VC(H) \left(\ln \left(\frac{2M}{VC(H)} \right) + 1 \right) + \ln \frac{4}{\delta} \right)}$$

 These bounds (and the preceding discussion) only work for binary classification, but there are generalizations