

CS 6347

Lecture 13

Maximum Likelihood Learning

Maximum Likelihood Estimation

- Given samples x^1, \dots, x^M from some unknown distribution with parameters θ ...
 - The **log-likelihood** of the evidence is defined to be

$$\log l(\theta) = \sum_m \log p(x|\theta)$$

- Goal: maximize the log-likelihood

MLE for Bayesian Networks

- Given samples x^1, \dots, x^M from some unknown Bayesian network that factors over the directed acyclic graph G
 - The parameters of a Bayesian model are simply the conditional probabilities that define the factorization
 - For each $i \in G$ we need to learn $p(x_i | x_{parents(i)})$, create a variable $\theta_{x_i | x_{parents(i)}}$

$$\log l(\theta) = \sum_m \sum_{i \in V} \log \theta_{x_i^m | x_{parents(i)}^m}$$

MLE for Bayesian Networks

$$\begin{aligned}\log l(\theta) &= \sum_m \sum_{i \in V} \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_m \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_{x_{\text{parents}(i)}} \sum_{x_i} N_{x_i, x_{\text{parents}(i)}} \log \theta_{x_i | x_{\text{parents}(i)}}\end{aligned}$$

MLE for Bayesian Networks

$$\begin{aligned}\log l(\theta) &= \sum_m \sum_{i \in V} \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_m \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_{x_{\text{parents}(i)}} \sum_{x_i} N_{x_i, x_{\text{parents}(i)}} \log \theta_{x_i | x_{\text{parents}(i)}}\end{aligned}$$

$N_{x_i, x_{\text{parents}(i)}}$ is the number of times
 $(x_i, x_{\text{parents}(i)})$ was observed in the samples

MLE for Bayesian Networks

$$\begin{aligned}\log l(\theta) &= \sum_m \sum_{i \in V} \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_m \log \theta_{x_i^m | x_{\text{parents}(i)}^m} \\ &= \sum_{i \in V} \sum_{x_{\text{parents}(i)}} \sum_{x_i} N_{x_i, x_{\text{parents}(i)}} \log \theta_{x_i | x_{\text{parents}(i)}}\end{aligned}$$

Fix $x_{\text{parents}(i)}$ solve for $\theta_{x_i | x_{\text{parents}(i)}}$ for all x_i
(on the board)

MLE for Bayesian Networks

$$\theta_{x_i|x_{\text{parents}(i)}} = \frac{N_{x_i, x_{\text{parents}(i)}}}{\sum_{x'_i} N_{x'_i, x_{\text{parents}(i)}}} = \frac{N_{x_i, x_{\text{parents}(i)}}}{N_{x_{\text{parents}(i)}}}$$

- This is just the empirical conditional probability distribution
 - Worked out nicely because of the factorization of the joint distribution
- Similar to the coin flips result from last time

MLE for MRFs

- Let's compute the MLE for MRFs that factor over the graph G as
$$p(x) = \frac{1}{Z(\theta)} \prod_C \psi_C(x_C | \theta)$$
- The parameters θ control the allowable potential functions
- Again, suppose we have samples x^1, \dots, x^M from some unknown MRF of this form

$$\log l(\theta) = \left[\sum_m \sum_C \log \psi_C(x_C^m | \theta) \right] - M \log Z(\theta)$$

MLE for MRFs

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$$\log l(\theta) = \left[\sum_m \sum_C \log \psi_C(x_C^m | \theta) \right] - M \log Z(\theta)$$

$Z(\theta)$ couples all of the potential functions together!

Even computing $Z(\theta)$ by itself was a challenging task...

Conditional Random Fields

- Learning MRFs is quite restrictive
 - Most “real” problems are really conditional models
- Example: image segmentation
 - Represent a segmentation problem as a MRF over a two dimensional grid
 - Each x_i is a binary variable indicating whether or not the pixel is in the foreground or the background
 - How do we incorporate pixel information?
 - The potentials over the edge (i, j) of the MRF should depend on x_i, x_j as well as the pixel information at nodes i and j

Feature Vectors

- The pixel information is called a **feature** of the model
 - Features will consist of more than just a scalar value (i.e., pixels, at the very least, are vectors of RGBA values)
- Vector of features y (e.g., one vector of features y_i for each $i \in V$)
 - We think of the joint probability distribution as a conditional distribution $p(x|y, \theta)$
- This makes MLE even harder
 - Samples are pairs $(x^1, y^1), \dots, (x^M, y^M)$
 - The feature vectors can be different for each sample: need to compute $Z(\theta, y^m)$ in the log-likelihood!

Log-Linear Models

- MLE seems daunting for MRFs and CRFs
 - Need a nice way to parameterize the model and to deal with features
- We often assume that the models are **log-linear** in the parameters
 - Many of the models that we have seen so far can easily be expressed as log-linear models of the parameters
 - Example: represent the s-t cut problem as a log-linear model (on the board)

Log-Linear Models

- Feature vectors should also be incorporated in a log-linear way
 - There is no fixed way to do this: it is up to you to decide how best to incorporate your feature information into the model
- The potential on the clique C should be a log-linear function of the parameters

$$\psi_C(x_C | y, \theta) = \exp(\langle \theta, f_C(x_C, y) \rangle)$$

- Here, f is a **feature map** that takes a collection of feature vectors and returns a vector
 - What might be a good feature map for image segmentation?

MLE for Log-Linear Models

$$p(x|y, \theta) = \frac{1}{Z(\theta, y)} \prod_c \exp(\langle \theta, f_c(x_c, y) \rangle)$$

$$\begin{aligned} \log l(\theta) &= \sum_m \left[\sum_c \langle \theta, f_c(x_c^m, y^m) \rangle \right] - \log Z(\theta, y^m) \\ &= \left\langle \theta, \sum_m \sum_c f_c(x_c^m, y^m) \right\rangle - \sum_m \log Z(\theta, y^m) \end{aligned}$$

MLE for Log-Linear Models

$$p(x|y, \theta) = \frac{1}{Z(\theta, y)} \prod_c \exp(\langle \theta, f_c(x_c, y) \rangle)$$

$$\log l(\theta) = \sum_m \left[\sum_c \langle \theta, f_c(x_c^m, y^m) \rangle \right] - \log Z(\theta, y^m)$$

$$= \underbrace{\left\langle \theta, \sum_m \sum_c f_c(x_c^m, y^m) \right\rangle}_{\text{Linear in } \theta} - \underbrace{\sum_m \log Z(\theta, y^m)}_{\text{Depends non-linearly on } \theta}$$

Linear in θ

Depends non-linearly
on θ

Concavity of MLE

We will show that $\log Z(\theta, y)$ is a convex function of θ ...

Fix a distribution $q(x|y)$

$$\begin{aligned} D(q||p) &= \sum_x q(x|y) \log \frac{q(x|y)}{p(x|y, \theta)} \\ &= \sum_x q(x|y) \log q(x|y) - \sum_x q(x|y) \log p(x|y, \theta) \\ &= -H(q) - \sum_x q(x|y) \log p(x|y, \theta) \\ &= -H(q) + \log Z(\theta, y) - \sum_x \sum_c q(x|y) \langle \theta, f_c(x_c, y) \rangle \\ &= -H(q) + \log Z(\theta, y) - \sum_c \sum_{x_c} q_c(x_c|y) \langle \theta, f_c(x_c, y) \rangle \end{aligned}$$

Concavity of MLE

$$\log Z(\theta, y) = \max_q \left[H(q) + \sum_C \sum_{x_C} q_C(x_C|y) \underbrace{\langle \theta, f_C(x_C, y) \rangle}_{\text{Linear in } \theta} \right]$$

- If a function $g(x, y)$ is convex in x for each y , then $\max_y g(x, y)$ is convex in y
 - As a result, $\log Z(\theta, y)$ is a convex function of θ

MLE for Log-Linear Models

$$p(x|y, \theta) = \frac{1}{Z(\theta, y)} \prod_c \exp(\langle \theta, f_c(x_c, y) \rangle)$$

$$\begin{aligned} \log l(\theta) &= \sum_m \left[\sum_c \langle \theta, f_c(x_c^m, y^m) \rangle \right] - \log Z(\theta, y^m) \\ &= \underbrace{\left\langle \theta, \sum_m \sum_c f_c(x_c^m, y^m) \right\rangle}_{\text{Linear in } \theta} - \underbrace{\sum_m \log Z(\theta, y^m)}_{\text{Convex in } \theta} \end{aligned}$$

Linear in θ

Convex in θ

MLE for Log-Linear Models

$$p(x|y, \theta) = \frac{1}{Z(\theta, y)} \prod_c \exp(\langle \theta, f_c(x_c, y) \rangle)$$

$$\begin{aligned} \log l(\theta) &= \sum_m \left[\sum_c \langle \theta, f_c(x_c^m, y^m) \rangle \right] - \log Z(\theta, y^m) \\ &= \underbrace{\left\langle \theta, \sum_m \sum_c f_c(x_c^m, y^m) \right\rangle - \sum_m \log Z(\theta, y^m)} \end{aligned}$$

Concave in θ

Could optimize it using gradient ascent!
(need to compute $\nabla_{\theta} \log Z(\theta, y)$)

MLE via Gradient Ascent

- What is the gradient of the log-likelihood with respect to θ ?

$$\nabla_{\theta} \log l(\theta) = ?$$

(worked out on board)

MLE via Gradient Ascent

- What is the gradient of the log-likelihood with respect to θ ?

$$\nabla_{\theta} \log l(\theta) = \sum_C \sum_{x_C} p_C(x_C | y, \theta) f_C(x_C, y)$$

- This is the expected value of the feature maps under the joint distribution
- To compute/approximate this quantity, we only need to compute/approximate the marginal distributions $p_C(x_C | y, \theta)$
- This requires performing marginal inference on a different model at each step of gradient ascent!