

CS 6347

Lecture 3

**More Bayesian Networks** 

## Recap



- Last time:
  - Complexity challenges
    - Representing distributions
    - Computing probabilities/doing inference
  - Introduction to Bayesian networks
- Today:
  - D-separation, I-maps, limits of Bayesian networks

# Bayesian Networks



- A Bayesian network is a directed graphical model that represents a subset of the independence relationships of a given probability distribution
  - Directed acyclic graph (DAG), G = (V, E)
    - Edges are still pairs of vertices, but the edges (1,2) and (2,1) are now distinct in this model
  - One node for each random variable
  - One conditional probability distribution per node
  - Directed edge represents a direct statistical dependence

# Bayesian Networks

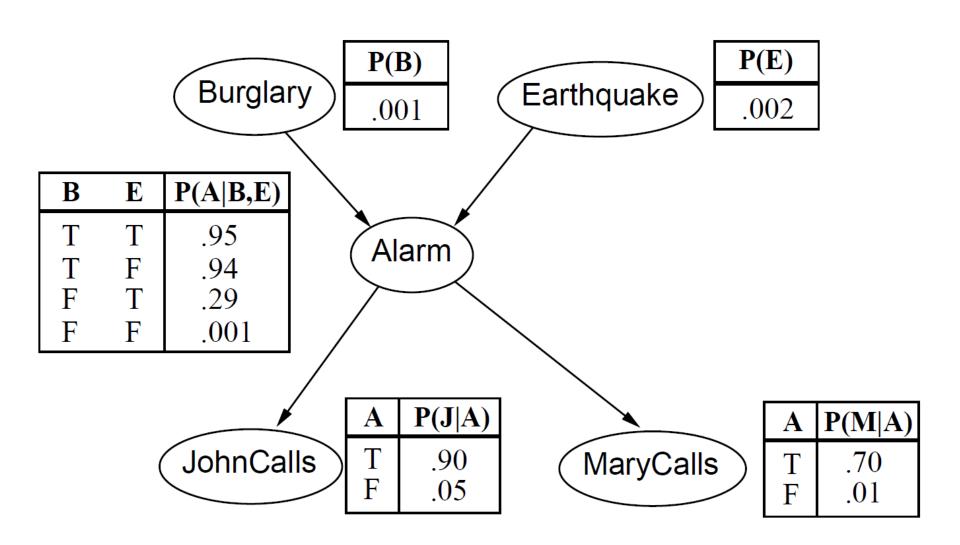


- A Bayesian network is a directed graphical model that represents a subset of the independence relationships of a given probability distribution
  - Encodes local Markov independence assumptions that each node is independent of its non-descendants given its parents
  - Corresponds to a factorization of the joint distribution

$$p(x_1, ..., x_n) = \prod_{i} p(x_i | x_{parents(i)})$$

## An Example





### **Directed Chain**

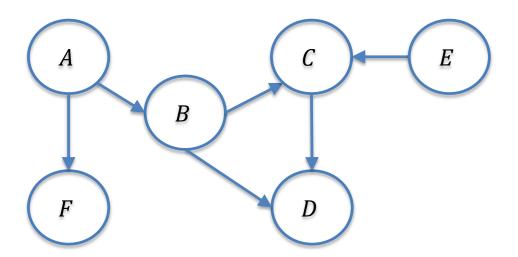


$$p(x_1, ..., x_n) = p(x_1)p(x_2|x_1)p(x_3|x_2) ... p(x_n|x_{n-1})$$



# Example:



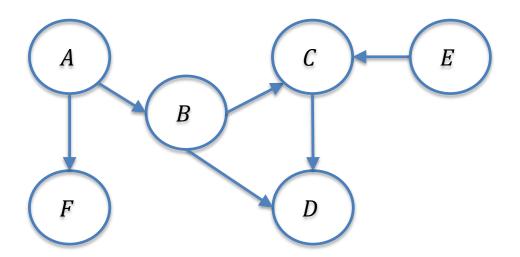


Suppose that a joint distribution factorizes over this graph...

- Local Markov independence relations?
- Joint distribution?

# Example:





The local Markov independence relations are not exhaustive:

 How can we figure out which independence relationships the model represents?

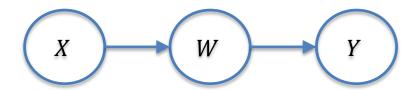


- Independence relationships can be figured out by looking at the graph structure!
  - Easier than looking at the tables and plugging into the definition
- We look at <u>all</u> of the paths from X to Y in the graph and determine whether or not they are <u>blocked</u>
  - $X \subset V$  is d-separated from  $Y \subset V$  given  $Z \subset V$  iff every path from X to Y in the graph is blocked by Z



Three types of situations can occur along any given path

(1) Sequential



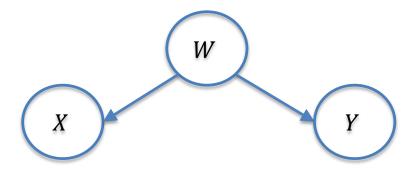
The path from *X* to *Y* is blocked if we condition on *W* 

Intuitively, if we condition on W, then information about X does not affect Y and vice versa



Three types of situations can occur along any given path

#### (2) Divergent



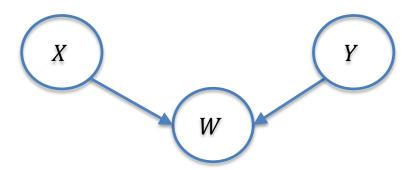
The path from *X* to *Y* is blocked if we condition on *W* 

If we don't condition on W, then information about W could affect the probability of observing either X or Y



Three types of situations can occur along any given path

#### (3) Convergent



The path from X to Y is blocked if we do not condition on W or any of its descendants

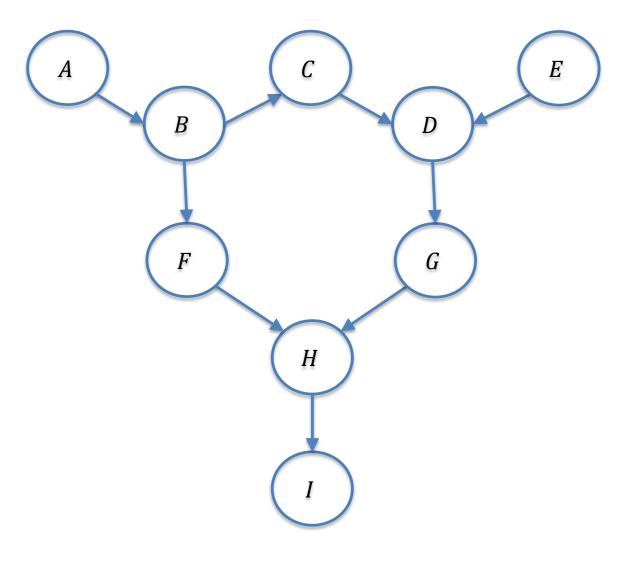
Conditioning on W couples the variables X and Y: knowing whether or not X occurs impacts the probability that Y occurs



- If the joint probability distribution factorizes with respect to the DAG G=(V,E), then X is d-separated from Y given Z implies  $X\perp Y\mid Z$ 
  - We can use this to quickly check independence assertions by using the graph
  - In general, these are only a subset of all independence relationships that are actually present in the joint distribution
  - If X and Y are not d-separated in G given Z, then there is some distribution that factorizes over G in which X and Y are dependent

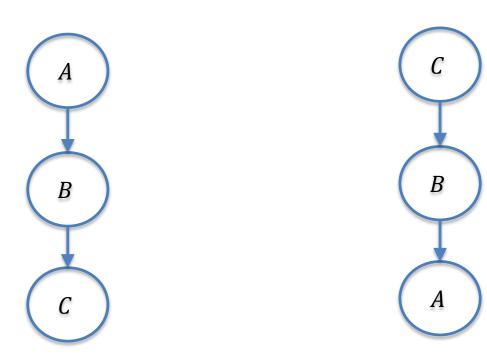
# **D-separation Example**





# **Equivalent Models?**

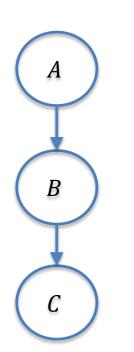


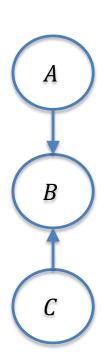


Do these models represent the same independence relations?

# **Equivalent Models?**



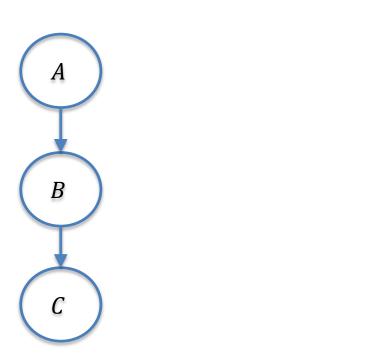




Do these models represent the same independence relations?

# **Equivalent Models?**





Do these models represent the same independence relations?

B



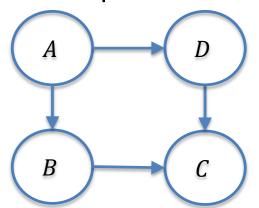
- Let I(p) be the set of all independence relationships in the joint distribution p and I(G) be the set of all independence relationships implied by the graph G
- We say that G is an I-map for I(p) if  $I(G) \subseteq I(p)$
- Theorem: the joint probability distribution, p, factorizes with respect to the DAG G=(V,E) iff G is an I-map for I(p)
- An I-map is perfect if I(G) = I(p)
  - Not always possible to perfectly represent all of the independence relations with a graph

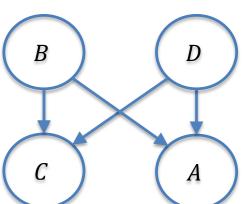
# Limits of Bayesian Networks



 Not all sets of independence relations can be captured by a Bayesian network, e.g., suppose these are the only independence relationships allowed

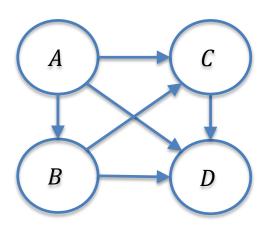
- $A \perp C \mid B, D$
- $B \perp D \mid A, C$
- Possible DAGs that represent only these independence relationships?





# Limits of Bayesian Networks

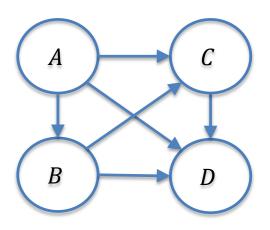




What independence relations does this model imply?

# Limits of Bayesian Networks





 $I(G) = \emptyset$ , this is an I-map for any joint distribution on four variables!