



CS 6347
Lecture 2

Bayesian Networks

Recap

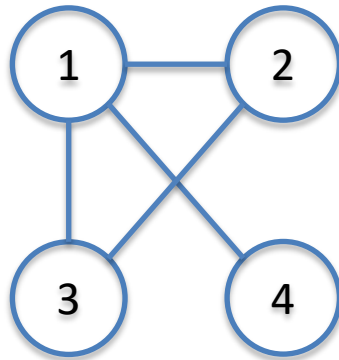


- Last time:
 - Course logistics
 - Review of basic probability
- Today:
 - Independent set example
 - What makes one probability distribution “better” than another?
 - Bayesian networks

Graphs & Independent Sets



- A **graph** $G = (V, E)$ is defined by a set of vertices V and a set of edges $E \subseteq V \times V$ (i.e., edges correspond to pairs of vertices)



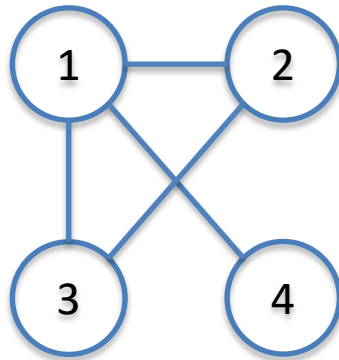
$$V = \{1,2,3,4\}$$

$$E = \{(1,2), (1,3), (2,3), (1,4)\}$$

Graphs & Independent Sets



- A set $S \subseteq V$ is an **independent set** if there does not exist an edge in E joining any pair of vertices in S



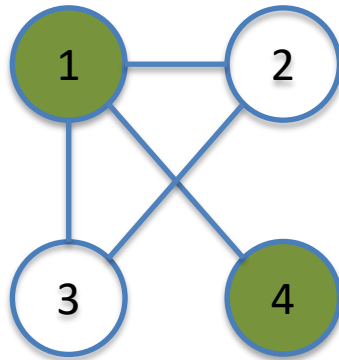
$$V = \{1,2,3,4\}$$

$$E = \{(1,2), (1,3), (2,3), (1,4)\}$$

Graphs & Independent Sets



- A set $S \subseteq V$ is an **independent set** if there does not exist an edge in E joining any pair of vertices in S



$$V = \{1,2,3,4\}$$

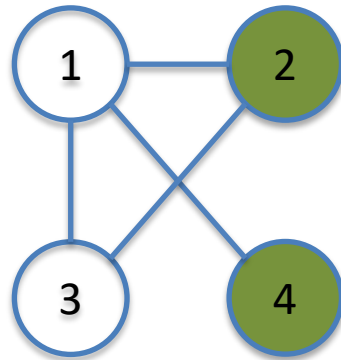
$$E = \{(1,2), (1,3), (2,3), (1,4)\}$$

{1,4} is not an independent set!

Graphs & Independent Sets



- A set $S \subseteq V$ is an **independent set** if there does not exist an edge in E joining any pair of vertices in S



$$V = \{1,2,3,4\}$$

$$E = \{(1,2), (1,3), (2,3), (1,4)\}$$

{2,4} is an independent set

Example: Independent Sets



- Let Ω be the set of all vertex subsets in a graph $G = (V, E)$
- Let p be the uniform probability distribution over all independent sets in Ω
- Define for each $i \in V$ and each subset of vertices S

$$\begin{aligned} X_i(S) &= 1, & \text{if } i \in S \text{ and} \\ X_i(S) &= 0, & \text{otherwise} \end{aligned}$$

- $p(X_i = 1)$ is the fraction of all independent sets in G containing i
- $p(x_V) \neq 0$ if and only if the x 's define an independent set

Example: Independent Sets

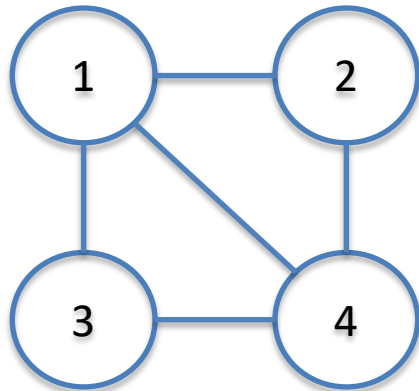


- Let Ω be the set of all vertex subsets in a graph $G = (V, E)$
- Let p be the uniform probability distribution over all independent sets in Ω
- Define for each $i \in V$ and each subset of vertices S

$$\begin{aligned} X_i(S) &= 1, & \text{if } i \in S \text{ and} \\ X_i(S) &= 0, & \text{otherwise} \end{aligned}$$

- $p(X_i = 1)$ is the fraction of all independent sets in G containing i
- $p(x_V) \neq 0$ if and only if the x 's define an independent set

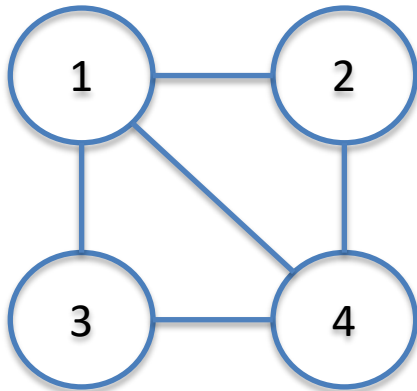
Example: Independent Sets



Consider the graph on the left, with the sample space and probabilities from the last slide

- $p(X_1 = 1, X_2 = 0, X_3 = 0, X_4 = 1) = ?$
- $p(X_1 = 0, X_2 = 1, X_3 = 1, X_4 = 0) = ?$
- $p(X_2 = 1) = ?$

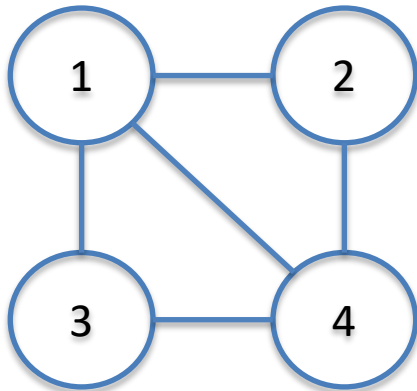
Example: Independent Sets



Consider the graph on the left, with the sample space and probabilities from the last slide

- $p(X_1 = 1, X_2 = 0, X_3 = 0, X_4 = 1) = 0$
- $p(X_1 = 0, X_2 = 1, X_3 = 1, X_4 = 0) = ?$
- $p(X_2 = 1) = ?$

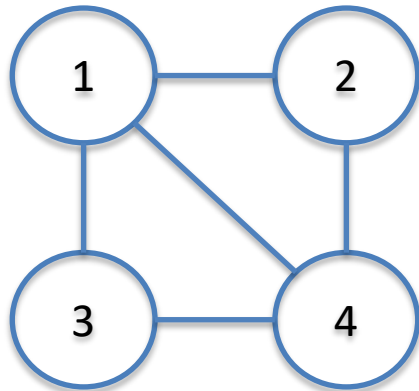
Example: Independent Sets



Consider the graph on the left, with the sample space and probabilities from the last slide

- $p(X_1 = 1, X_2 = 0, X_3 = 0, X_4 = 1) = 0$
- $p(X_1 = 0, X_2 = 1, X_3 = 1, X_4 = 0) = 1/6$
- $p(X_2 = 1) = ?$

Example: Independent Sets



Consider the graph on the left, with the sample space and probabilities from the last slide

- $p(X_1 = 1, X_2 = 0, X_3 = 0, X_4 = 1) = 0$
- $p(X_1 = 0, X_2 = 1, X_3 = 1, X_4 = 0) = 1/6$
- $p(X_2 = 1) = 1/3$

Example: Independent Sets



- How large of a table is needed to store an arbitrary distribution $p(X_V)$ over subsets of a given graph $G = (V, E)$?

Example: Independent Sets



- How large of a table is needed to store an arbitrary distribution $p(X_V)$ over subsets of a given graph $G = (V, E)$?

$$2^{|V|}-1$$

Computational Issue #1



- How much storage space is required to represent a given joint probability distribution?
 - Can we do better than the worst case?
 - What properties of the joint distribution affect this number?

- Consider a general joint distribution $p(X_1, \dots, X_n)$ over binary valued random variables
- If X_1, \dots, X_n are mutually independent random variables, then

$$p(x_1, \dots, x_n) = p(x_1) \dots p(x_n)$$

- How much information is needed to store the joint distribution?

?

- Consider a general joint distribution $p(X_1, \dots, X_n)$ over binary valued random variables
- If X_1, \dots, X_n are mutually independent random variables, then

$$p(x_1, \dots, x_n) = p(x_1) \dots p(x_n)$$

- How much information is needed to store the joint distribution?

n numbers

- This model is boring: knowing the value of any one variable tells you nothing about the others

- Consider a general joint distribution $p(X_1, \dots, X_n)$ over binary valued random variables
- If X_1, \dots, X_n are mutually, conditionally independent given a different random variable Y , then

$$p(x_1, \dots, x_n | y) = p(x_1 | y) \dots p(x_n | y)$$

and

$$p(y, x_1, \dots, x_n) = p(y)p(x_1 | y) \dots p(x_n | y)$$

- These models turn out to be surprisingly powerful, despite looking nearly identical to the previous case!

- Consider a different joint distribution $p(X_1, \dots, X_n)$ over **binary** valued random variables
- Suppose, for $i > 2$, X_i is independent of X_1, \dots, X_{i-2} given X_{i-1}

$$\begin{aligned} p(x_1, \dots, x_n) &= p(x_1)p(x_2|x_1) \dots p(x_n|x_1, \dots, x_{n-1}) \\ &= p(x_1)p(x_2|x_1)p(x_3|x_2) \dots p(x_n|x_{n-1}) \end{aligned}$$

- How much storage is needed to represent this model?

?

- This distribution is chain-like

- Consider a different joint distribution $p(X_1, \dots, X_n)$ over **binary** valued random variables
- Suppose, for $i > 2$, X_i is independent of X_1, \dots, X_{i-2} given X_{i-1}

$$\begin{aligned} p(x_1, \dots, x_n) &= p(x_1)p(x_2|x_1) \dots p(x_n|x_1, \dots, x_{n-1}) \\ &= p(x_1)p(x_2|x_1)p(x_3|x_2) \dots p(x_n|x_{n-1}) \end{aligned}$$

- How much storage is needed to represent this model?

$$2n - 1$$

- This distribution is chain-like

- Given a joint probability distribution (as a table), how complicated is it to compute individual probabilities?
 - Computing $p(X_1 = x_1)$ from a joint probability distribution $p(X_1 = x_1, \dots, X_n = x_n)$ is one type of **statistical inference**

- Given a joint distribution $p(X_1, \dots, X_n)$, the **marginal distribution** over the i^{th} random variable is given by

$$p_i(X_i = x_i) = \sum_{x_1} \sum_{x_2} \dots \sum_{x_{i-1}} \sum_{x_{i+1}} \dots \sum_{x_n} p(X_1 = x_1, \dots, X_n = x_n)$$

- In general, marginal distributions are obtained by fixing some subset of the variables and summing out over the others
 - This can be an expensive operation!

- Given fixed values of some subset, E , of the random variables, compute the conditional probability over the remaining variables, S

$$p(X_S | X_E = x_E) = \frac{p(X_S, X_E = x_E)}{p(X_E = x_E)}$$

- This involves computing the marginal distribution $p(X_E = x_E)$, so we refer to this as **marginal inference**

- Given fixed values of some subset, E , of the random variables, compute the most likely assignment of the remaining variables, S

$$\operatorname{argmax}_{x_S} p(X_S = x_S | X_E = x_E)$$

- This is called maximum a posteriori **(MAP) inference**
- We don't need to do marginal inference to compute the MAP assignment, why not?

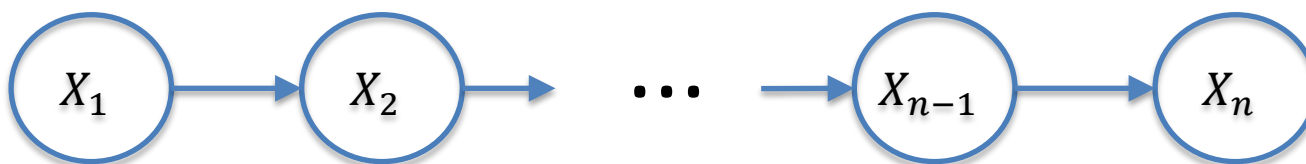
- The amount of storage and the complexity of statistical inference are both affected by the independence structure of the joint probability distribution
 - More independence means easier computation and less storage
 - Want models that somehow make the underlying independence assumptions explicit, so we can take advantage of them (expensive to check all of the possible independence relationships)

- A **Bayesian network** is a directed graphical model that represents independence relationships of a given probability distribution
 - Directed acyclic graph (DAG), $G = (V, E)$
 - Edges are still pairs of vertices, but the edges (1,2) and (2,1) are now distinct in this model
 - One node for each random variable
 - One conditional probability distribution per node
 - Directed edge represents a direct statistical dependence

- A **Bayesian network** is a directed graphical model that represents independence relationships of a given probability distribution
- Encodes **local Markov** independence assumptions that each node is independent of its non-descendants given its parents
- Corresponds to a **factorization** of the joint distribution

$$p(x_1, \dots, x_n) = \prod_i p(x_i | x_{parents(i)})$$

$$p(x_1, \dots, x_n) = p(x_1)p(x_2|x_1)p(x_3|x_2) \dots p(x_n|x_{n-1})$$



An Example

