

# Principle Component Analysis 

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## Eigenvalues

- $\lambda$ is an eigenvalue of a matrix $A \in \mathbb{R}^{n \times n}$ if the linear system $A x=\lambda x$ has at least one non-zero solution
- If $A x=\lambda x$ we say that $\lambda$ is an eigenvalue of $A$ with corresponding eigenvector $x$
- Could be multiple eigenvectors for the same $\lambda$


## Eigenvalues of Symmetric Matrices

- If $A \in \mathbb{R}^{n \times n}$ is symmetric, then it has $n$ linearly independent eigenvectors $v_{1}, \ldots, v_{n}$ corresponding to $n$ real eigenvalues
- Moreover, it has $n$ linearly independent orthonormal eigenvectors
- $v_{i}^{T} v_{j}=0$ for all $i \neq j$
- $v_{i}^{T} v_{i}=1$ for all $i$


## Eigenvalues of Symmetric Matrices

- If $A \in \mathbb{R}^{n \times n}$ is symmetric, then it has $n$ linearly independent eigenvectors $v_{1}, \ldots, v_{n}$ corresponding to $n$ real eigenvalues
- A symmetric matrix $A$ is positive definite if and only if all of its eigenvalues are positive or equivalently $x^{T} A x>0$ for all vectors $x \neq 0$
- The orthonormal eigenvectors form a basis of $\mathbb{R}^{n}$ (similar to the standard coordinate axes)


## Examples

- The $2 \times 2$ identity matrix has all of its eigenvalues equal to 1 (it is positive definite) with orthonormal eigenvectors $\left[\begin{array}{l}1 \\ 0\end{array}\right]$ and $\left[\begin{array}{l}0 \\ 1\end{array}\right]$
- The matrix $\left[\begin{array}{ll}1 & 1 \\ 1 & 1\end{array}\right]$ has eigenvalues 0 and 2 with orthonormal
eigenvectors $\left[\begin{array}{c}\frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}}\end{array}\right]$ and $\left[\begin{array}{c}\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}}\end{array}\right]$
- The matrix $\left[\begin{array}{ll}2 & 1 \\ 1 & 2\end{array}\right]$ has eigenvalues 1 and 3 with orthonormal eigenvectors $\left[\begin{array}{c}\frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}}\end{array}\right]$ and $\left[\begin{array}{c}\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}}\end{array}\right]$


## Eigenvalues

- Suppose $A \in \mathbb{R}^{n \times n}$ is symmetric
- Any $x \in \mathbb{R}^{n}$ can be written as $x=\sum_{i=1}^{n} c_{i} v_{i}$ where $v_{1}, \ldots, v_{n}$ are the eigenvectors of $A$
- $A x=\sum_{i=1}^{n} \lambda_{i} c_{i} v_{i}$
- $A^{2} x=\sum_{i=1}^{n} \lambda_{i}^{2} c_{i} v_{i}$
- $A^{t} x=\sum_{i=1}^{n} \lambda_{i}^{t} c_{i} v_{i}$


## Eigenvalues

- Suppose $A \in \mathbb{R}^{n \times n}$ is symmetric
- Any $x \in \mathbb{R}^{n}$ can be written as $x=\sum_{i=1}^{n} c_{i} v_{i}$ where $v_{1}, \ldots, v_{n}$ are the eigenvectors of $A$
- $c_{i}=v_{i}^{T} x$, this is the projection of $x$ along the line given by $v_{i}$ (assuming that $v_{i}$ is a unit vector)


## Eigenvalues of Symmetric Matrices

- Let $Q \in \mathbb{R}^{n \times n}$ be the matrix whose $i^{\text {th }}$ column is $v_{i}$ and $D \in$ $\mathbb{R}^{n \times n}$ be the diagonal matrix such that $D_{i i}=\lambda_{i}$
- $A x=Q D Q^{T} x$
- Can throw away some eigenvectors to approximate this quantity
- For example, let $Q_{k}$ be the matrix formed by keeping only the top $k$ eigenvectors and $D_{k}$ be the diagonal matrix whose diagonal consists of the top $k$ eigenvalues


## Frobenius Norm

- The Frobenius norm is a matrix norm given by

$$
\|A\|_{F}=\sqrt{\sum_{i=1}^{n} \sum_{j=1}^{n}\left|A_{i j}\right|^{2}}
$$

- $Q_{k} D_{k} Q_{k}^{T}$ is the best rank $k$ approximation of the symmetric matrix $A$ with respect to the Frobenius norm


## Principal Component Analysis

- Principle component analysis
- Can be used to reduce the dimensionality of the data while still maintaining a good approximation of the sample mean and variance
- Can also be used for selecting good features that are combinations of the input features
- Unsupervised - just finds a good representation of the data in terms of combinations of the input features


## Principal Component Analysis

- Input a collection of data points sampled from some distribution $x_{1}, \ldots, x_{p} \in \mathbb{R}^{n}$
- Construct the matrix $W \in \mathbb{R}^{n \times p}$ whose $i^{\text {th }}$ column is

$$
x_{i}-\frac{\sum_{j} x_{j}}{p}
$$

- The matrix $W W^{T}$ is the sample covariance matrix
- $W W^{T}$ is symmetric and positive semidefinite


## Principal Component Analysis

- PCA finds a set of orthogonal vectors that best explain the variance of the sample covariance matrix
- From our previous discussion, these are exactly the eigenvectors of $W W^{T}$
- We can discard the eigenvectors corresponding to small magnitude eigenvalues to yield an approximation
- Simple algorithm to describe, MATLAB and other programming languages have built in support for eigenvector computation


## PCA in Practice

- Forming the matrix $W W^{T}$ can require a lot of memory (especially if $n>p$ )
- Need a faster way to compute this without forming the matrix explicitly
- Typical approach: use the singular value decomposition


## Singular Value Decomposition (SVD)

- Every matrix $B \in \mathbb{R}^{n \times p}$ admits a decomposition of the form

$$
B=U \Sigma V^{T}
$$

- where $U \in \mathbb{R}^{n \times n}$ is an orthogonal matrix, $\Sigma \in \mathbb{R}^{n \times p}$ is nonnegative diagonal matrix, and $V \in \mathbb{R}^{p \times p}$ is an orthogonal matrix
- A matrix $C \in \mathbb{R}^{m \times m}$ is orthogonal if $C^{T}=C^{-1}$. Equivalently, the rows and columns of $C$ are orthonormal vectors


## Singular Value Decomposition (SVD)

- Every matrix $B \in \mathbb{R}^{n \times p}$ admits a decomposition of the form

$$
B=U \Sigma V^{T} \quad \begin{aligned}
& \text { Diagonal elements of } \Sigma \text { called } \\
& \text { singular values }
\end{aligned}
$$

- where $U \in \mathbb{R}^{n \times n}$ is an orthogonal matrix, $\Sigma \in \mathbb{R}^{n \times p}$ is nonnegative diagonal matrix, and $V \in \mathbb{R}^{p \times p}$ is an orthogonal matrix
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## SVD and PCA

- Returning to PCA
- Let $W=U \Sigma V^{T}$ be the SVD of $W$
- $W W^{T}=U \Sigma V^{T} V \Sigma^{T} U^{T}=U \Sigma \Sigma^{T} U^{T}$
- If we can compute the SVD of $W$, then we don't need to form the matrix $W W^{T}$


## SVD and PCA

- For any matrix $A, A A^{T}$ is symmetric and positive semidefinite
- Let $A=U \Sigma V^{T}$ be the SVD of $A$
- $A A^{T}=U \Sigma V^{T} V \Sigma^{T} U^{T}=U \Sigma \Sigma^{T} U^{T}$
- $U$ must be a matrix of eigenvectors of $A A^{T}$
- The eigenvalues of $A A^{T}$ are all non-negative because $\Sigma \Sigma^{T}=$ $\Sigma^{2}$ which are the square of the singular values of $A$


## An Example: "Eigenfaces"

- Let's suppose that our data is a collection of images of the faces of individuals



## An Example: "Eigenfaces"

- Let's suppose that our data is a collection of images of the faces of individuals
- The goal is, given the "training data", to correctly match new images to the training data
- Let's suppose that each image is an $\mathrm{s} \times s$ array of pixels: $x_{i} \in$ $R^{n}, n=s^{2}$
- As before, construct the matrix $W \in \mathbb{R}^{n \times p}$ whose $i^{t h}$ column is $x_{i}-\sum_{j} \frac{x_{j}}{p}$


## An Example: "Eigenfaces"

- Forming the matrix $W W^{T}$ requires a lot of memory
- $s=256$ means $W W^{T}$ is $65536 \times 65536$
- Need a faster way to compute this without forming the matrix explicitly
- Could use the singular value decomposition


## An Example: "Eigenfaces"

- A different approach when $p \ll n$
- Compute the eigenvectors of $A^{T} A$ (this is an $p \times p$ matrix)
- Let $v$ be an eigenvector of $A^{T} A$ with eigenvalue $\lambda$
- $A A^{T} A v=\lambda A v$
- This means that $A v$ is an eigenvector of $A A^{T}$ with eigenvalue $\lambda$ (or 0)
- Save the top $k$ eigenvectors - called eigenfaces in this example


## An Example: "Eigenfaces"

- The data in the matrix is "training data"
- Given a new image, we'd like to determine which, if any, member of the data set that it is most similar to
- Step 1: Compute the projection of the recentered, new image onto each of the $k$ eigenvectors
- This gives us a vector of weights $c_{1}, \ldots, c_{k}$


## An Example: "Eigenfaces"

- The data in the matrix is "training data"
- Given a new image, we'd like to determine which, if any, member of the data set that it is most similar to
- Step 2: Determine if the input image is close to one of the faces in the data set
- If the distance between the input and it's approximation is too large, then the input is likely not a face


## An Example: "Eigenfaces"

- The data in the matrix is "training data"
- Given a new image, we'd like to determine which, if any, member of the data set that it is most similar to
- Step 3: Find the person in the training data that is closest to the new input
- Replace each group of training images by its average
- Compute the distance to the $i^{t h}$ average $\left\|c-a^{i}\right\|$ where $a^{i}$ are the coefficients of the average face for person $i$

