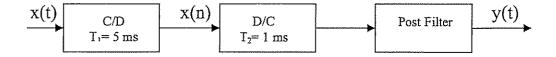
DSP Ex Am 1 - 2004

1. (20 points)

Consider the simple signal processing system shown in the figure below. The sampling periods of the C/D (continuous-to-digital) and D/C converters are T_1 = 5 ms and T_2 = 1 ms, respectively. Determine the output y(t) of the system, if the input is given by

$$x(t) = 3 \cos 100\pi t + 2 \sin 250\pi t$$

The post-filter is an ideal low pass filter with a cutoff frequency of 500 Hz.



The input $x(n) = \{1,2,-1, \gamma\}$ to a LTI system with an impulse response $\{1,\alpha,\beta,2\}$ yields an output $y(n) = \{1,4,2,0,9,-4,4\}$. What is the output $y_1(n)$ of the LTI system due to an input $x_1(n) = \{1,0,-1\}$?

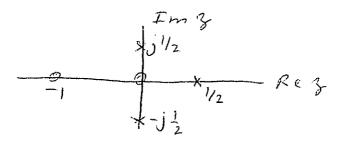
The following LCCDE describes the input-output relationship of a causal, LTI system; determine the impulse response, h (n) of the LTI system.

$$y(n) - \frac{1}{2}y(n-1) + \frac{1}{4}y(n-2) = x(n) - \frac{1}{4}x(n-1)$$

(Note: Your answer for h(n) should contain only real coefficients to receive credit.)

When the input to an L II system is $x(n) = (1/3)^n u(n) + (2)^n u(-n-1)$, the corresponding output is given by $y(n) = 5 (1/3)^n u(n) - 5 (2/3)^n u(n)$. (a) Find the system transfer function H (z), and indicate the region of convergence, (b) Sketch the Direct Form II (canonical or minimum delays) implementation of the system, and (c) Is the system stable? Is it causal?

The z-transform of the sequence x (n) is denoted by X (z). The pole-zero plot of X (z) is shown in the figure below. There are 3 finite poles (z=1/2, +/-1/2 j), and 2 finite zeros (z=0, -1). Sketch the pole-zero plots of (a) $X_1(z)$, where $x_1(n) = x$ (1-n), and (b) $X_2(z)$, where $x_2(n) = (1/2)^n x(n)$. Gain factor is unity



6. (20 points)

Determine the impulse response h(n) of the causal L- II system implemented as shown below, without using z-transforms.

