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MLE Parameter Learning for Bayesian networks

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What we will cover

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Vibhav Gogate University of Texas, Dallas Type of Data sets:

- Fully observed
- Partially observed

Tasks:

- Parameter Learning
- Structure Learning

Approach:

Maximum likelihood estimation approach

Bayesian approach

8 combinations and we will study the 2 highlighted combinations.

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PART 1

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> Fully Observed Data Parameter Learning MLE approach

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Maximum Likelihood Estimation principles

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Vibhav Gogate University of Texas, Dallas Single variable example: A biased coin

- Two outcomes: *head* and *tail*
- Data set: Tosses of the biased coin
- Task: Estimate the probability of heads/tails on the next flip
- Assumption: the process is controlled by a probability distribution Pr(x) where x ∈ {h, t}

Value of $Pr(x = h) = \theta$ if 60 out of 100 tosses yield heads.

MLE scoring for the coin example

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Evaluation metric: How well we can predict the data?

- Example data: H, H, T, H, T
- Likelihood of data = $\prod_i \Pr(x_i) = \theta.\theta.(1-\theta).\theta.(1-\theta)$



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MLE scoring for the coin example: Analytical derivation

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Vibhav Gogate University of Texas, Dallas Distribution: $Pr(x = h) = \theta$ and $Pr(x = t) = 1 - \theta$.

Log-Likelihood function

$$LogL(\theta) = \log(\theta^{\#heads}.(1 - \theta)^{\#tails})$$

= #heads. log(θ) + #tails. log(1 - θ)

- MLE Aim: Find θ^* such that $LogL(\theta^*)$ is maximum.
- Differentiate the likelihood function with respect to θ and set the derivative to zero. We get:

$$\theta^* = rac{\#heads}{\#heads + \#tails}$$

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Extending the MLE principle to a Bayesian network

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Vibhav Gogate University of Texas. Dallas Given a Bayesian network $Pr(x) = \prod_{i=1}^{n} \theta_{x_i | pa(x_i)}$ Decomposition of Likelihood function

$$L(\theta, \mathcal{D}) = \prod_{j=1}^{m} \Pr(x^{(j)})$$
$$= \prod_{j=1}^{m} \prod_{i=1}^{n} \theta_{x_{i}^{(j)} \mid pa(x_{i}^{(j)})}$$
$$= \prod_{i=1}^{n} \prod_{j=1}^{m} \theta_{x_{i}^{(j)} \mid pa(x_{i}^{(j)})}$$

 Each term is a conditional likelihood of a variable given its parents

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Extending the MLE principle to a Bayesian network

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Vibhav Gogate University of Texas, Dallas Given a Bayesian network $Pr(x) = \prod_{i=1}^{n} \theta_{x_i | pa(x_i)}$

$$\mathcal{L}(heta, \mathcal{D}) = \prod_{i=1}^n \prod_{j=1}^m heta_{x_i^{(j)} \mid \mathsf{pa}(x_i^{(j)})}$$

Let #(x_i, pa(x_i)) be the number of times the tuple (x_i, pa(x_i)) appears in the data set. We can write Likelihood function as:

$$L(\theta, \mathcal{D}) = \prod_{i=1}^{n} \theta_{x_i | pa(x_i)}^{\#(x_i, pa(x_i))}$$

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Extending the MLE principle to a Bayesian network

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Vibhav Gogate University of Texas, Dallas Given a Bayesian network $Pr(x) = \prod_{i=1}^{n} \theta_{x_i | pa(x_i)}$

Given (fully observed) data \mathcal{X} , MLE solution is:

$$heta^*_{x_i \mid \textit{pa}(x_i)} = rac{\#(x_i, \textit{pa}(x_i))}{\#(\textit{pa}(x_i))}$$

where $\#(x_i, pa(x_i))$ is the number of times the tuple $(x_i, pa(x_i))$ appears in \mathcal{X} . $\#(pa(x_i))$ is the number of times the tuple $pa(x_i)$ appears in \mathcal{X} .

• $\#(x_i, pa(x_i))$ is called the sufficient statistic.

Any function of the data is called a statistic. A sufficient statistic is a statistic that contains all of the information in the data set that is needed for a particular estimation task.

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MLE Learning example: Bayesian network





Н	θ_{H}^{m}	h	S	1/6	h	е	11/1
h	3/4	h	\overline{s}	5/6	h	ē	1/12
ħ	1/4	\overline{h}	5	1/4	ħ	е	1/2
		ħ	5	3/4	ħ	ē	1/2

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MLE Learning: Bayesian network (fully observable case)

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Vibhav Gogate University of Texas, Dallas Impact of data set size

- ML estimate will have different values depending upon the size of the data set
- The variance of the estimate will decrease as the data set increases in size.

Theorem:

The distribution of the ML estimate is asymptotically normal and can be approximated by a Gaussian with mean $Pr(x_i|pa(x_i))$ and variance:

 $\frac{\Pr(x_i|pa(x_i)) \times (1 - \Pr(x_i|pa(x_i)))}{N \times \Pr(pa(x_i))}$

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Issue: $Pr(pa(x_i))$ should not be too small.

PART 2

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Partially Observed Data Parameter Learning MLE approach

- Examples: missing data, hidden variables, some variables are just not observable
- Gradient Ascent (Not covered)
- Expectation maximization (The EM algorithm)

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Partially Observed Data (POD)



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- Missing data, hidden variables
- *H*, *T*, *H*, ?, *T*, ?, ...
- Why is the data missing?
 - Randomly missing
 - Deliberately missing

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Why is parameter learning in presence of POD challenging?

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$$L(\theta, \mathcal{X}) = \prod_{j=1}^{m} \sum_{\mathbf{y} \notin \mathbf{x}^{(j)}} \Pr_{\theta}(\mathbf{x}^{(j)}, \mathbf{y})$$

Compare with Likelihood function for FOD:

$$L(\theta, \mathcal{X}) = \prod_{j=1}^{m} \Pr_{\theta}(\mathbf{x}^{(j)})$$

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Likelihood function for POD:

Likelihood function for POD:

- is not unimodal.
- cannot be expressed in closed form
- is not decomposable

Why is parameter learning in presence of POD challenging?

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POD case:

Each point in the sum yields a unimodal distribution. When combined, we get a multi-modal distribution. FOD case: Unimodal distribution

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The optimization problem, a.k.a. maximizing our objective, the likelihood of the data is hard. We need an iterative approach.

Approach 1: The Expectation Maximization (EM) Algorithm

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- Start with random parameters
- Repeat until convergence
 - 1 Complete the incomplete data using current parameters.
 - 2 Update the parameters based on the completed data

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STEP 1: computes expected sufficient statistics (E-step) STEP 2: maximizes the likelihood (M-step)

The Expectation Maximization Algorithm: Example



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 $\begin{array}{l} \theta_{a} = .3\\ \theta_{b} = .9\\ \theta_{c|\bar{a},\bar{b}} = .83\\ \theta_{c|\bar{a},b} = .09\\ \theta_{c|\bar{a},\bar{b}} = .6\\ \theta_{c|\bar{a},b} = .2\\ \theta_{d|\bar{c}} = .1\\ \theta_{d|c} = .8 \end{array}$

Data instance: $(a,?,?,\overline{d})$ How to complete this example?

For each possible completion

- STEP 1: Compute how likely the completion is.
- STEP 2: Data set is now weighted

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The Expectation Maximization Algorithm: E-Step

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Vibhav Gogate University of Texas, Dallas Data set is now bigger and weighted

- ($a, ?, ?, \overline{d}$) corresponds to four weighted examples
 - (a, b, c, \overline{d}) , weight = .0492
 - (a, b, \bar{c}, \bar{d}), weight = .8852
 - (a, \bar{b}, c, \bar{d}), weight = .0164
 - ($a, \bar{b}, \bar{c}, \bar{d}$), weight = .0492
- Intuition is nice. But if a large number of values are missing, the amount of computation involved is huge!!! (exponential in the number of missing values).
- Fortunately, we only need to estimate the sufficient statistics which do not require access to the completed data.

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The Expectation Maximization Algorithm: M-Step

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Vibhav Gogate University of Texas, Dallas Updating: $\theta_{d|\bar{c}}$

Unweighted MLE estimate:

$$heta_{d|ar{m{c}}} = rac{\#(m{d},ar{m{c}})}{\#(ar{m{c}})}$$

Weighted MLE estimate:

$$heta_{d|ar{c}} = rac{\textit{TotalWeight}(d,ar{c})}{\textit{TotalWeight}(ar{c})} = rac{\sum_{j=1}^{m} \Pr_{ heta}(d,ar{c}|\mathbf{x}^{(j)})}{\sum_{j=1}^{m} \Pr_{ heta}(ar{c}|\mathbf{x}^{(j)})}$$

 $\Pr_{\theta}(d, \bar{c} | \mathbf{x}^{(j)})$ and $\Pr_{\theta}(\bar{c} | \mathbf{x}^{(j)})$ are the conditional marginal probabilities of the partial assignments (d, \bar{c}) and \bar{c} given evidence $\mathbf{x}^{(j)}$ and the current setting of parameters θ . They can be computed using variable elimination or belief propagation.

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EM: Properties

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- EM may converge to different parameters, with different likelihoods, depending on the initial estimates θ⁽⁰⁾ that it starts with.
- Each iteration of the EM algorithm will have to perform inference on a Bayesian network.
- In each iteration, the algorithm computes the probability of each instantiation (*x*, **u**) given each example as evidence.
- All of these computations correspond to posterior marginals over network families. Namely, the require inference. That is why inference is the key problem in Bayesian networks.

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EM: Properties

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- EM parameter estimates are the only estimates that maximize the expected log-likelihood function
- EM is indeed searching for estimates that maximize the expected log-likelihood function, which also explains its name.
- Parameters that maximize the expected log-likelihood function cannot decrease the log-likelihood function.
 - Each iteration of EM can only increase the likelihood and never decrease it.

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It will always converge to a local maxima.