

## *Controlflow-based Coverage Criteria*

W. Eric Wong  
Department of Computer Science  
The University of Texas at Dallas  
ewong@utdallas.edu  
<http://www.utdallas.edu/~ewong>

---

## Speaker Biographical Sketch

---

- Professor & Director of International Outreach  
Department of Computer Science  
University of Texas at Dallas
- Guest Researcher  
Computer Security Division  
National Institute of Standards and Technology (NIST)
- Vice President, IEEE Reliability Society
- Secretary, ACM SIGAPP (Special Interest Group on Applied Computing)
- Principal Investigator, NSF TUES (Transforming Undergraduate Education in Science, Technology, Engineering and Mathematics) Project
  - *Incorporating Software Testing into Multiple Computer Science and Software Engineering Undergraduate Courses*
- Founder & Steering Committee co-Chair for the SERE conference  
(*IEEE International Conference on Software Security and Reliability*)  
(<http://paris.utdallas.edu/sere13>)





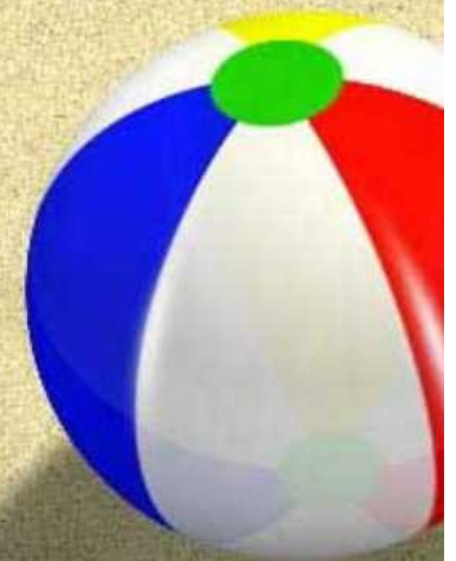
---

## *Outline*

---

- Block/Statement Coverage
- Decision Coverage
- Condition Coverage
- Multiple Condition Coverage

*Statement and Block Coverage*



## Declarations and Basic Blocks

- Any program written in a procedural language consists of a sequence of statements. Some of these statements are *declarative*, such as the *#define* and *int* statements in C, while others are *executable*, such as the *assignment*, *if*, and *while* statements in C and Java.
- Recall that a **basic block** is a sequence of consecutive statements that has exactly one entry point and one exit point.
  - For any procedural language, adequacy with respect to the statement coverage and block coverage criteria are defined next.
- **Notation:**  $(P, R)$  denotes program  $P$  subject to requirement  $R$ .

## Statement Coverage

- The statement coverage of  $T$  with respect to  $(P, R)$  is computed as  $S_c / (S_e - S_i)$ , where  $S_c$  is the number of statements covered,  $S_i$  is the number of *unreachable statements*, and  $S_e$  is the *total number of executable statements* in the program, i.e., the size of the coverage domain.
- $T$  is considered **adequate** with respect to the statement coverage criterion if the statement coverage of  $T$  with respect to  $(P, R)$  is 1.

## Block Coverage

- The block coverage of  $T$  with respect to  $(P, R)$  is computed as  $B_c / (B_e - B_i)$ , where  $B_c$  is the number of blocks covered,  $B_i$  is the number of *unreachable blocks*, and  $B_e$  is the total number of *executable blocks* in the program, i.e., the size of the block coverage domain.
- $T$  is considered **adequate** with respect to the block coverage criterion if the statement coverage of  $T$  with respect to  $(P, R)$  is 1.

## Example: Statement Coverage

- Coverage domain:  $S_e = \{4, 5, 6, 7, 8, 9, 12, 13\}$  Let  $T_1 = \{t_1: \langle x = -1, y = -1 \rangle, t_2: \langle x = 1, y = 1 \rangle\}$
- Statements covered:
  - $t_1$ : 4, 5, 6, 7, 8 and 13
  - $t_2$ : 4, 5, 6, 12, and 13
- $S_c = 7, S_i = 1, S_e = 8$ . The statement coverage for  $T_1$  is  $7 / (8 - 1) = 1$ . Hence we conclude that  $T_1$  is **adequate** for  $(P, R)$  with respect to the statement coverage criterion. Note: *9 is unreachable*.

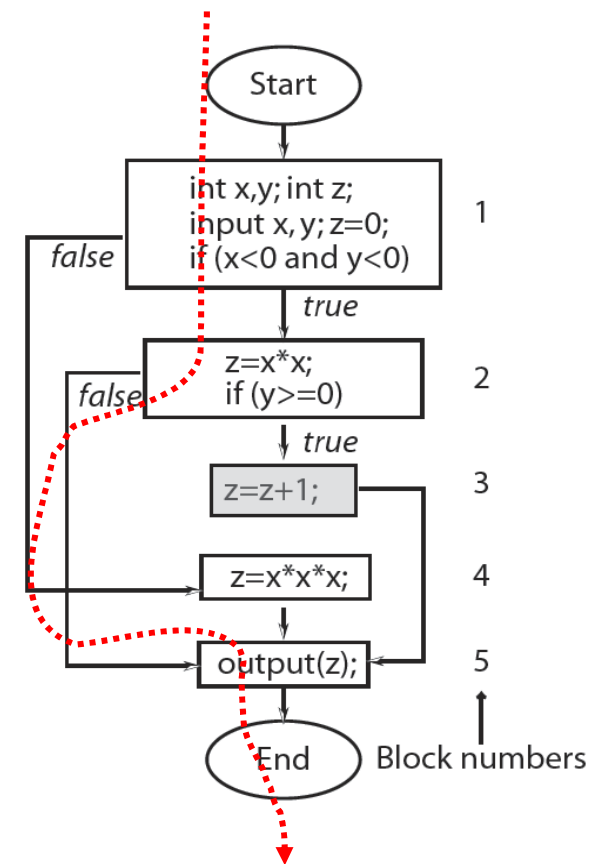
```
1   begin
2   int X, Y;
3   int Z;
4   input (X, Y);
5   Z = 0;
6   if (X < 0 and Y < 0) {
7       Z = X*X;
8       if (Y >= 0)
9           Z = Z + 1;
10  }
11  else
12      Z = X*X*X;
13  output (Z);
14  end
```



## Example: Block Coverage (1)

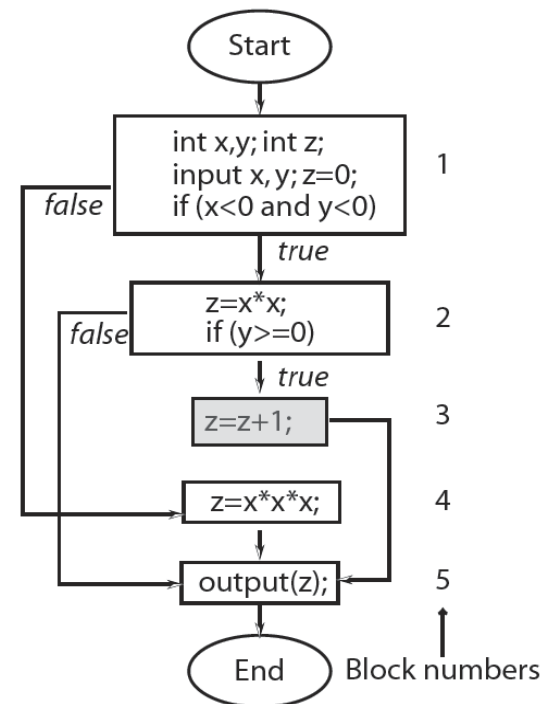
- Coverage domain:  $B_e = \{1, 2, 3, 4, 5\}$
- Blocks covered:
  - $t_1$ : Blocks 1, 2, 5
  - $t_2, t_3$ : same coverage as of  $t_1$ .
- $B_e = 5$ ,  $B_c = 3$ ,  $B_i = 1$ .
  - Block coverage for  $T_2 = 3 / (5 - 1) = 0.75$ .
  - Hence  $T_2$  is **not adequate** for  $(P, R)$  with respect to the block coverage criterion.

$$T_2 = \left\{ \begin{array}{l} t_1 : \langle x = -1 \quad y = -1 \rangle \\ t_2 : \langle x = -3 \quad y = -1 \rangle \\ t_3 : \langle x = -1 \quad y = -3 \rangle \end{array} \right\}$$



## Example: Block Coverage (2)

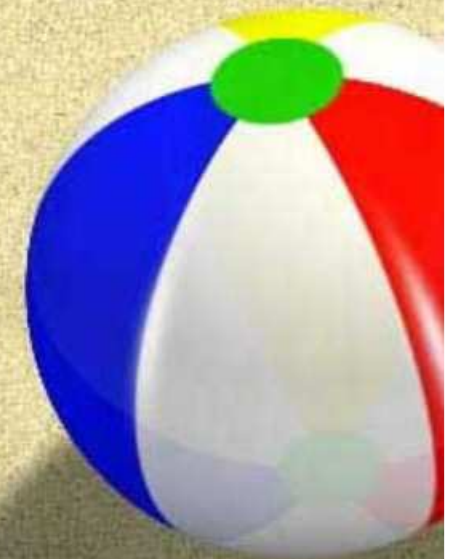
- $T_1$  is adequate w.r.t. block coverage criterion. **Verify this statement!**
- Also, if test  $t_2$  in  $T_1$  is added to  $T_2$ , we obtain a test set adequate with respect to the block coverage criterion for the program under consideration.
- **Verify this statement!**



## Coverage Values

- The formulae given for computing various types of code coverage yield *a coverage value between 0 and 1*. However, while specifying a coverage value, *one might instead use percentages*. For example, a statement coverage of 0.65 is the same as 65% statement coverage.

*Condition and Decision Coverage*



## Conditions

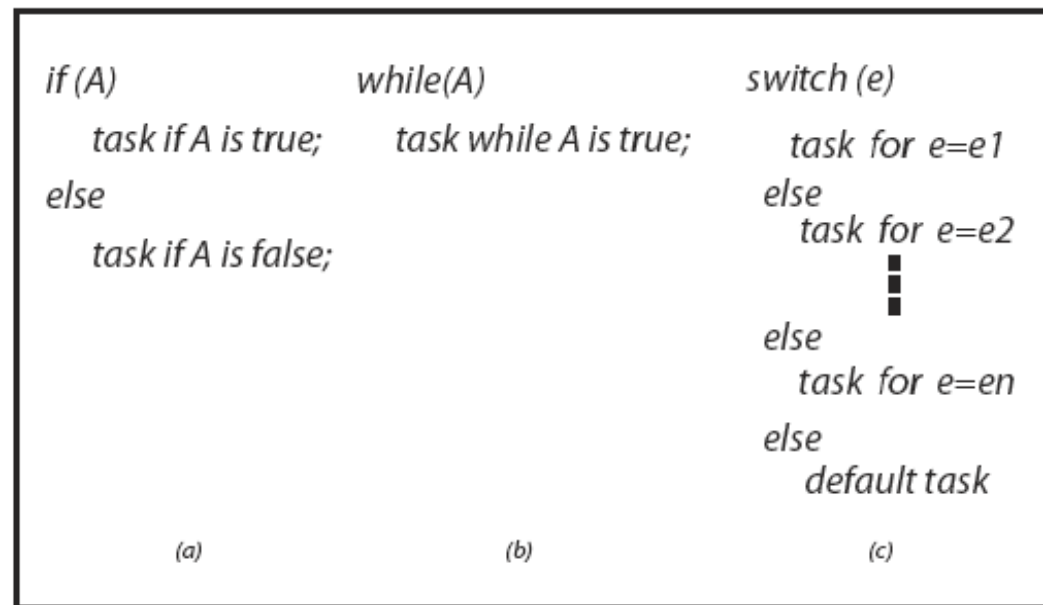
- Any expression that evaluates to **true** or **false** constitutes a **condition**. Such an expression is also known as a **predicate**.
- Given that A, B, and D are Boolean variables, and  $x$  and  $y$  are integers, A,  $x > y$ , A OR B, A AND ( $x < y$ ), (A AND B) are sample conditions.
- Note that in programming language C,  $x$  and  $x + y$  are valid conditions, and the *constants 1 and 0* correspond to, respectively, *true and false*.

## *Simple and Compound Conditions*

- A *simple condition* does not use any Boolean operators except for the **not** operator. It is made up of variables and *at most one* relational operator from the set  $\{<, \leq, >, \geq, ==, \neq\}$ .
- *Simple conditions* are also referred to as **atomic** or **elementary** conditions because they cannot be parsed any further into two or more conditions.
- A *compound condition* is made up of two or more simple conditions joined by one or more Boolean operators.

## Conditions as Decisions

- *Any condition can serve as a decision* in an appropriate context within a program. Most high level languages provide *if*, *while*, and *switch* statements to serve as contexts for decisions.





---

## *Outcomes of a Decision*

---

- A decision can have three possible outcomes: **true**, **false**, and **undefined**.
- In some cases the evaluation of a condition might fail in which case the corresponding decision's outcome is undefined.



## Undefined Condition

- The condition inside the **if** statement on line 6 will remain undefined *because the loop at lines 2-4 will never end*. Thus the decision on line 6 evaluates to **undefined**.

```
1  bool foo(int a_parameter){
2      while (true) { // An infinite loop.
3          a_parameter=0;
4      }
5  } // End of function foo().
:
:
6  if(x < y and foo(y)){ // foo() does not terminate.
7      compute(x,y);
:
:
```

## Coupled Conditions

- How many simple conditions are there in the compound condition:  
 $D = (A \text{ AND } B) \text{ OR } (C \text{ AND } A)$ ? *The first occurrence of A is said to be coupled to its second occurrence.*
- Does D contain *three or four simple conditions*? Both answers are correct depending on one's point of view. Indeed, there are three distinct conditions A , B, and C. The answer is four when one is interested in the *number of occurrences* of simple conditions in a compound condition.

## Conditions within Assignments

- Strictly speaking, a condition becomes a decision only when it is used in the appropriate context such as within an **if** statement.
- At line 4,  $x < y$  does not constitute a decision and neither does  $A \times B$ .
  1.  $A = x < y$ ; // A simple condition assigned to a Boolean variable A.
  2.  $X = P \text{ or } Q$ ; // A compound condition assigned to a Boolean variable  $x$
  3.  $x = y + z \times s$ ; **if**( $x$ )...// The condition will be true if  $x = 1$  and false otherwise
  4.  $A = x < y$ ;  $x = A \times B$ ; // A is used in a subsequent expression for  $x$  but not as a decision

## Decision Coverage

- A decision is considered **covered** if the flow of control has been diverted to **all possible destinations** that correspond to this decision, i.e., *all outcomes of the decision have been taken*.
- This implies that, for example, the expression in the **if** or a **while** statement has evaluated to **true** in some execution of the program under test and to **false** in the same or another execution.



---

## *Decision Coverage: Switch Statement*

---

- Decision implied by *the switch statement* is considered covered if during one or more executions of the program under test the flow of control has been *diverted to all possible destinations*.

## Decision Coverage: Example (1)

- Requirement:
  - The following code inputs an integer  $x$ , and if  $x < 0$ , transforms it into a positive value before invoking `foo-1` to compute the output  $z$ .
  - It is supposed to compute  $z$  using `foo-2` when  $x \geq 0$ .
  - It has a bug.

```
1  begin
2  int X, Z;
3  input (x);
4  if(x<0)
5  X =-X;
6  z=foo-1(x);
7  output(z);
8  end
```

There should have been an `else` clause before this statement.

## Decision Coverage: Example (2)

- Consider the test set  $T = \{t_1: \langle x = -5 \rangle\}$ .
  - It is adequate with respect to *statement and block* coverage criteria, but does not reveal the bug.
- Another test set  $T' = \{t_1: \langle x = -5 \rangle \ t_2: \langle x = 3 \rangle\}$  does reveal the bug. It covers the decision whereas  $T$  does not. **Check!**
- This example illustrates *how and why decision coverage might help in revealing a bug that is not revealed* by a test set adequate with respect to *statement and block coverage*.

```
1  begin
2  int X, Z;
3  input (x);
4  if(x<0)
5  x =-x;
6  z=foo-1(x);
7  output(z);
8  end
```

There should have been an `else` clause before this statement.

## Decision Coverage: Computation

- The **decision coverage** of  $T$  with respect to  $(P, R)$  is computed as  $D_c / (D_e - D_i)$ , where  $D_c$  is the number of decisions covered.
- $D_i$  is the number of infeasible decisions, and  $D_e$  is the total number of decisions in the program, i.e., the size of the decision coverage domain.
- $T$  is considered *adequate* with respect to the decision coverage criterion if the decision coverage of  $T$  with respect to  $(P, R)$  is 1.





---

## *Decision Coverage: Domain*

---

- The domain of decision coverage consists of *all decisions in the program under test.*

## Condition Coverage

- A decision can be composed of *a simple condition* such as  $x < 0$ , or of *a more complex condition*, such as  $((x < 0 \text{ AND } y < 0) \text{ OR } (p \geq q))$ .
- AND, OR, XOR are the *logical operators* that connect two or more simple conditions to form a *compound condition*.
- *A simple condition is considered covered if it evaluates to true and false in one or more executions* of the program in which it occurs.
- *A compound condition is considered covered if each simple condition it is comprised of is also covered.*

## Decision and Condition Coverage (1)

- Decision coverage is concerned with *the coverage of decisions regardless of* whether or not a decision corresponds to *a simple or a compound* condition. Thus in the statement

1. `if (x < 0 and y < 0) {`
2. `z = foo(x, y)`

### Question

`if (x < 0)`

`if (y < 0)`

`z=foo(x, y);`

**How many decision?**

- There is *only one decision* that leads control to line 2 if the compound condition inside the *if* evaluates to **true**.
- However, a compound condition might evaluate to **true** or **false** *in one of several ways*.

## Decision and Condition Coverage (2)

- Referring to the following code
  1. `if (x < 0 and y < 0) {`
  2. `z = foo(x, y)`
- The condition at line 1 evaluates to **false** when  $x \geq 0$  regardless of the value of  $y$ .
- Another condition, such as `(x < 0 OR y < 0)`, evaluates to **true** regardless of the value of  $y$ , when  $x < 0$ .
- With this evaluation characteristic in view, compilers often generate code that uses **short circuit** evaluation of compound conditions.

## Decision and Condition Coverage (3)

- Here is a possible translation:

```
1  if (x < 0 and y < 0) {  
2    z=foo(x,y);  
    }  
    →  
1  if (x<0)  
2    if (y<0)  
3      z=foo(x,y);
```

- We now see two decisions, one corresponding to each simple condition in the *if* statement.

## Condition Coverage

- The *condition coverage* of  $T$  with respect to  $(P, R)$  is computed as  $C_c / (C_e - C_i)$ , where
  - $C_c$  is the number of simple conditions covered,
  - $C_i$  is the number of infeasible simple conditions, and
  - $C_e$  is the total number of simple conditions in the program.
- $T$  is considered adequate with respect to the condition coverage criterion if the condition coverage of  $T$  with respect to  $(P, R)$  is 1.
- An alternate formula where each simple condition contributes 2, 1, or 0 to  $C_c$  depending on whether it is covered, partially covered, or not covered, respectively, is:

$$\frac{C_c}{2 \times (C_e - C_i)}$$

## Condition Coverage: Example (1)

- Partial specifications for computing  $z$

$x < 0$	$y < 0$	Output ( $z$ )
true	true	foo1(x,y)
true	false	foo2(x,y)
false	true	foo2(x,y)
false	false	foo1(x,y)

```
1  begin
2  int x, y, z;
3  input (x, y);
4  if(x<0 and y<0)
5      z=foo1(x,y);
6  else
7      z=foo2(x,y);
8  output(z);
9  end
```

This program has a bug based on the specification.

## Condition Coverage: Example (2)

- Consider the test set

$$T = \{t_1 : \langle x = -3, y = -2 \rangle \quad t_2 : \langle x = -4, y = -2 \rangle\}$$

- **Check** that T is adequate with respect to the *statement, block, and decision* coverage criteria and the program behaves correctly against  $t_1$  and  $t_2$ .
- $C_c = 1$ ,  $C_e = 2$ ,  $C_i = 0$ . Hence, condition coverage for  $T = 0.5$ .

```
1  begin
2    int x, y, z;
3    input (x, y);
4    if(x<0 and y<0)
5      z=foo1(x,y);
6    else
7      z=foo2(x,y);
8    output(z);
9  end
```



## Condition Coverage: Example (3)

- Add the following test case to  $T$ :  $t_3: \langle x = 3, y = 4 \rangle$
- Check that the enhanced test set  $T$  is adequate with respect to the *condition coverage criterion* and possibly reveals a bug in the program.
  - The program shows  $z = \text{foo2}(x, y)$
  - But the specifications says  $z = \text{foo1}(x, y)$
- Under what conditions will the bug be revealed by  $t_3$ ?

```
1  begin
2  int x, y, z;
3  input (x, y);
4  if(x<0 and y<0)
5  z=foo1(x,y);
6  else
7  z=foo2(x,y);
8  output(z);
9  end
```

## Condition/Decision Coverage

- When a decision is composed of a compound condition, decision coverage **does not imply** that each simple condition within a compound condition has taken both values **true** and **false**.
- **Condition coverage** ensures that each component simple condition within a condition has taken both values **true** and **false**.
- Question: **Does the condition coverage require each decision to take all its outcomes?**

## Condition/Decision Coverage: Example

- Consider the following program and two test sets.

```
1  begin
2    int x, y, z;
3    input (x, y);
4    if(x<0 or y<0)
5      z=foo-1(x,y);
6    else
7      z=foo-2(x,y);
8    output(z);
9  end
```

$$T_1 = \left\{ \begin{array}{l} t_1 : \langle x = -3 \quad y = -2 \rangle \\ t_2 : \langle x = 4 \quad y = -2 \rangle \end{array} \right\}$$

$$T_2 = \left\{ \begin{array}{l} t_1 : \langle x = -3 \quad y = 2 \rangle \\ t_2 : \langle x = 4 \quad y = -2 \rangle \end{array} \right\}$$

- In-class exercise:**
  - Is  $T_1$  is adequate with respect to decision coverage?
  - Is  $T_1$  is adequate with respect to condition coverage?
  - How about  $T_2$ ?

## Condition/Decision Coverage: Definition

- The condition/decision coverage of  $T$  with respect to  $(P, R)$  is computed as  $(C_c + D_c) / ((C_e - C_i) + (D_e - D_i))$ , where
  - $C_c$  is the number of **simple conditions** covered
  - $D_c$  is the number of **decisions** covered,
  - $C_e$  and  $D_e$  are the number of simple conditions and decisions respectively
  - $C_i$  and  $D_i$  are the number of infeasible simple conditions and decisions, respectively.

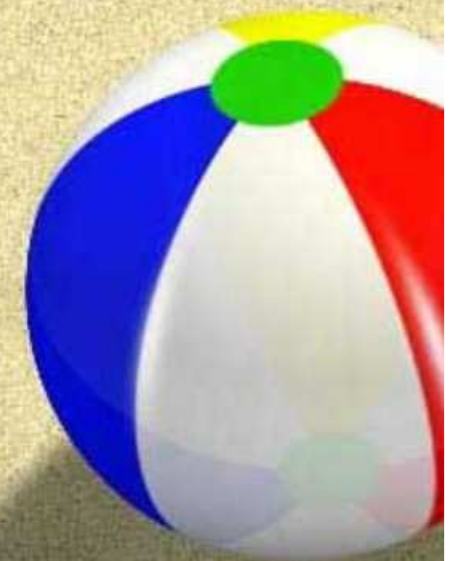
## Condition/Decision Coverage: Example

- **In-class exercise:** Is  $T$  adequate with respect to the condition/decision coverage criterion?

```
1  begin
2    int x, y, z;
3    input (x, y);
4    if(x<0 or y<0)
5      z=foo-1(x,y);
6    else
7      z=foo-2(x,y);
8    output(z);
9  end
```

$$T = \left\{ \begin{array}{l} t_1 : \langle x = -3 \quad y = -2 \rangle \\ t_2 : \langle x = 4 \quad y = 2 \rangle \end{array} \right\}$$

*Multiple Condition Coverage*



## Multiple Condition Coverage

- Consider *a compound condition with two or more simple conditions*.  
Using condition coverage on some compound condition C implies that each simple condition within C needs to be evaluated to **true** and **false**.
- **However, does it imply that all combinations of the values of the individual simple conditions in C have been exercised?**

## *Multiple Condition Coverage/Simple Condition Coverage*

- Multiple condition coverage versus simple condition coverage is similar to uni-dimensional equivalence class partitioning versus multi-dimensional equivalence partitioning.
  - ➔ *considered separately* versus *considered simultaneously*



## Multiple Condition Coverage: Example

- Consider  $D = (A < B) \text{ OR } (A > C)$  composed of two simple conditions  $A < B$  and  $A > C$ . The four possible combinations of the outcomes of these two simple conditions are enumerated in the table.
  - **Check:** Is  $T$  100% w.r.t. the decision coverage?
  - **Check:** Is  $T$  100% w.r.t. the condition coverage?
  - **Check:** Does  $T$  cover all four combinations?
  - **Check:** Does  $T'$  cover all four combinations?

	$A < B$	$A > C$	$D$
1	true	true	true
2	true	false	true
3	false	true	true
4	false	false	false

$$T = \left\{ \begin{array}{l} t_1: \langle A = 2 \quad B = 3 \quad C = 1 \rangle \\ t_2: \langle A = 2 \quad B = 1 \quad C = 3 \rangle \end{array} \right\}$$

$$T' = \left\{ \begin{array}{l} t_1: \langle A = 2 \quad B = 3 \quad C = 1 \rangle \\ t_2: \langle A = 2 \quad B = 1 \quad C = 3 \rangle \\ t_3: \langle A = 2 \quad B = 3 \quad C = 5 \rangle \\ t_4: \langle A = 2 \quad B = 1 \quad C = 5 \rangle \end{array} \right\}$$

## Multiple Condition Coverage: Definition (1)

- Suppose that the program under test contains a total of  $n$  decisions. Assume also that each decision contains  $k_1, k_2, \dots, k_n$  simple conditions. Each decision has several combinations of values of its constituent simple conditions.
- For example, decision  $i$  will have a total of  $2^{k_i}$  combinations. Thus **the total number of combinations** to be covered is

$$\sum_{i=1}^n 2^{k_i}$$

## Multiple Condition Coverage: Definition (2)

- The **multiple condition** coverage of  $T$  with respect to  $(P, R)$  is computed as  $C_c / (C_e - C_i)$ , where:
  - $C_c$  is the number of **combinations** covered,
  - $C_i$  is the number of **infeasible simple combinations**, and
  - $C_e$  is the **total number of combinations** in the program.
- $T$  is considered adequate with respect to the multiple condition coverage criterion if the condition coverage of  $T$  with respect to  $(P, R)$  is 1.

## Multiple Condition Coverage: Example (1)

- Consider the following program with specifications in the table.

```
1  begin
2  int A, B, C, S=0;
3  input (A, B, C);
4  if(A<B and A>C) S=f1(A, B, C);
5  if(A<B and A≤C) S=f2(A, B, C);
6  if(A≥B and A≤C) S=f4(A, B, C);
7  output(S);
8  end
```

	$A < B$	$A > C$	$S$
1	true	true	$f1(P, Q, R)$
2	true	false	$f2(P, Q, R)$
3	false	true	$f3(P, Q, R)$
4	false	false	$f4(P, Q, R)$

- There is **an obvious bug** in the program: computation of  $S$  for one of the four combinations, line 3 in the table, has been left out.

## Multiple Condition Coverage: Example (2)

- Is  $T$  adequate w.r.t. decision coverage?
- Multiple condition coverage?
- Does it reveal the bug?

```
1  begin
2  int A, B, C, S=0;
3  input (A, B, C);
4  if(A<B and A>C) S=f1(A, B, C);
5  if(A<B and A≤C) S=f2(A, B, C);
6  if(A≥B and A≤C) S=f4(A, B, C);
7  output(S);
8  end
```

$$T = \left\{ \begin{array}{l} t_1 : \langle A = 2 \quad B = 3 \quad C = 1 \rangle \\ t_2 : \langle A = 2 \quad B = 1 \quad C = 3 \rangle \end{array} \right\}$$

## Multiple Condition Coverage: Example (3)

- Is  $T'$  100% with respect to the decision coverage?
- Does  $T'$  reveal the bug?

```
1  begin
2  int A, B, C, S=0;
3  input (A, B, C);
4  if(A<B and A>C) S=f1(A, B, C);
5  if(A<B and A≤C) S=f2(A, B, C);
6  if(A≥B and A≤C) S=f4(A, B, C);
7  output(S);
8  end
```

$$T' = \left\{ \begin{array}{l} t_1 : \langle A = 2, B = 3, C = 1 \rangle \\ t_2 : \langle A = 2, B = 1, C = 3 \rangle \\ t_3 : \langle A = 2, B = 3, C = 5 \rangle \end{array} \right\}$$

## Multiple Condition Coverage: Example (4)

- **In-class exercise:**
  - Is  $T'$  100% w.r.t. simple condition coverage?
  - Is  $T'$  100% w.r.t. multiple condition coverage?
- Now add a test to  $T'$  to cover the uncovered combinations.
  - Does your test reveal the bug?
  - If yes, then under what conditions?